

# Module Assembly in ALICE ITS Upgrade

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## Outline

- Motivation
- Concept Design of ALICE/ITS Module Assembly
- Conclusion and Outlook

Beam pipe

Outer layers

Middle layers

Inner layers

- Contribute to ALICE ITS upgrade project, **targeting at heavy flavor physics**
- Learn high precision and automatic assembly technique and **transfer it to PLAC/HFEE applications**

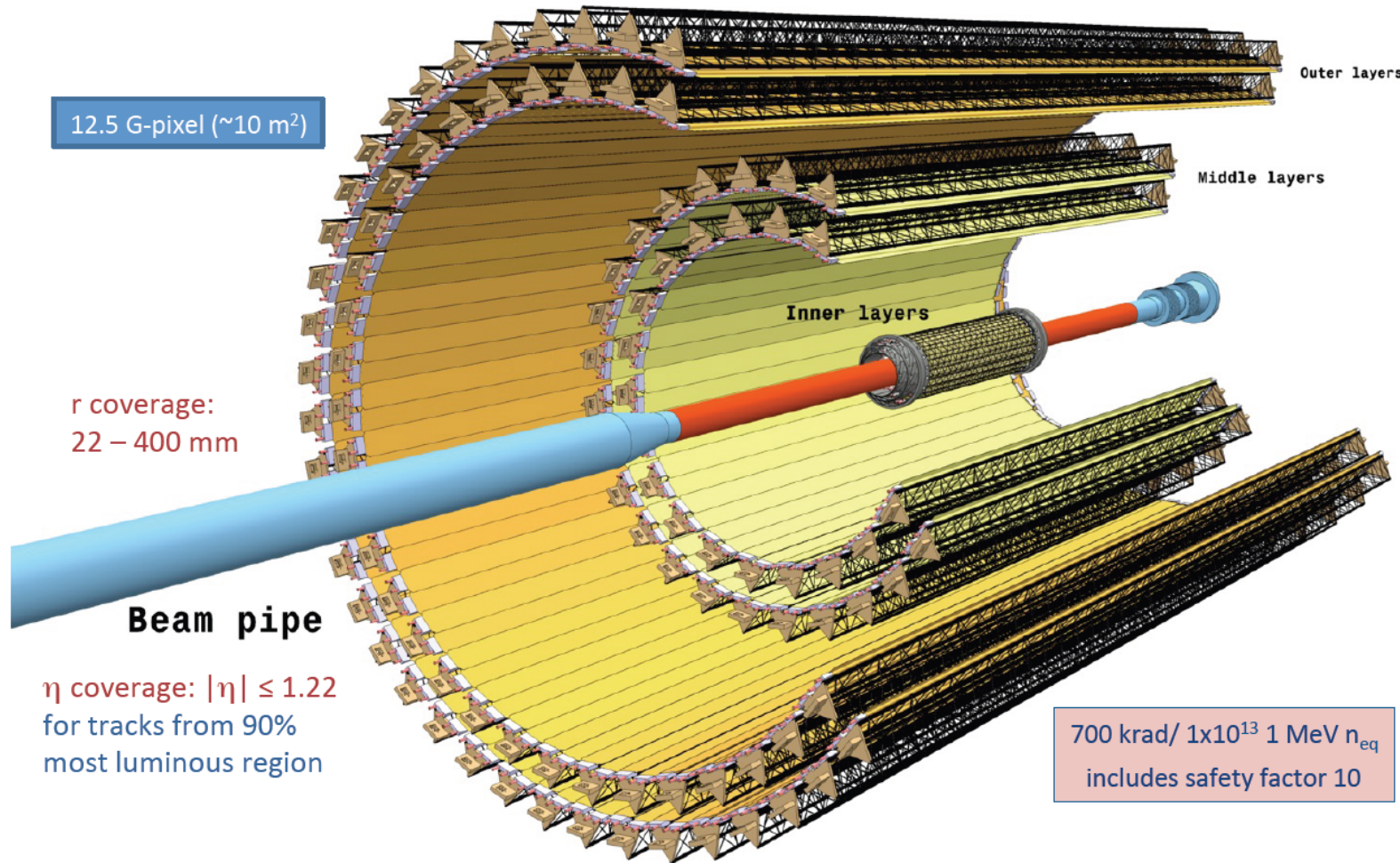
**Following contents are mostly from V. Manzari (Bari/INFN) and A. Di Mauro (CERN)'s talks at "4<sup>th</sup> ALICE ITS upgrade, MFT and O<sup>2</sup> Asian Workshop 2014@Pusan"**



# Concept Design of ALICE/ITS Module Assembly

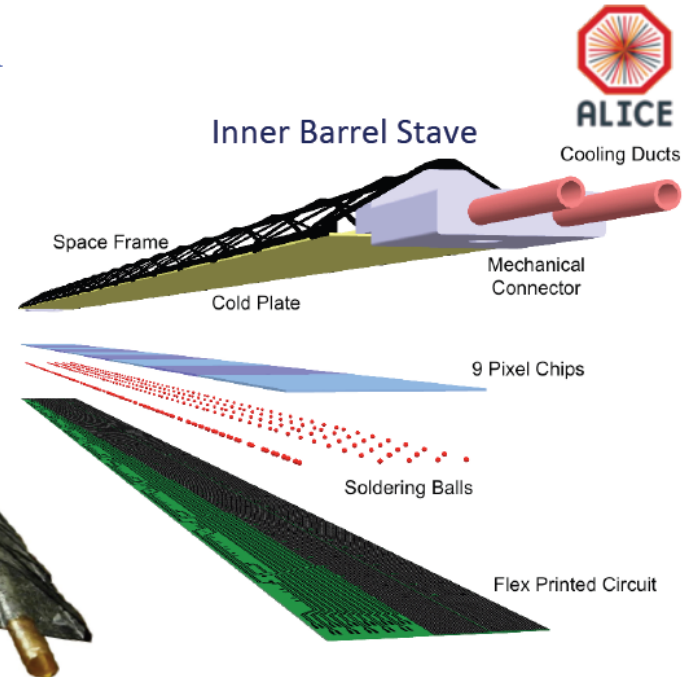
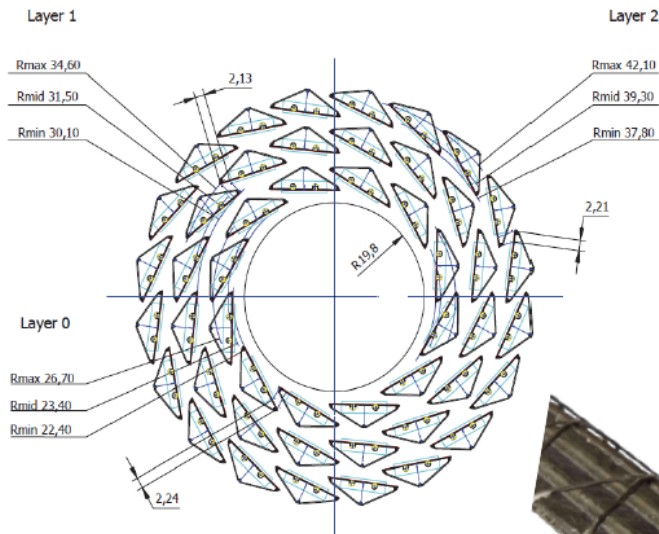
## Detector Layout Overview

7 layers of Monolithic Active Pixel Sensors



# Concept Design of ALICE/ITS Module Assembly

## Inner Barrel



### Inner Barrel (IB): 3 Inner Layers

Radial position (mm): 23, 31, 39

Length in z (mm): 271

Nr. of staves: 12, 16, 20

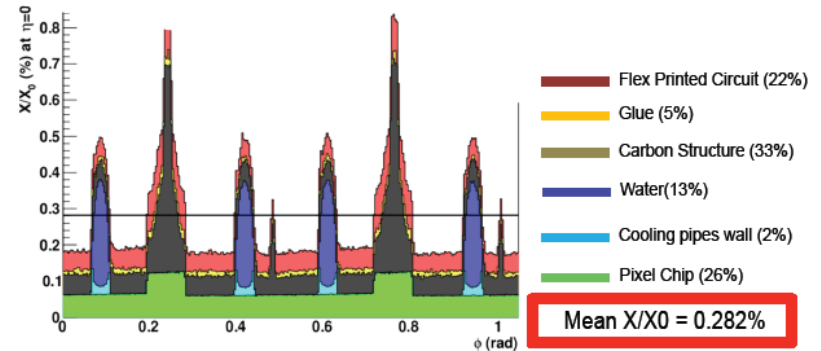
Nr. of modules/stave: 1

Nr. of chips/module: 9

Nr. of chips/layer: 108, 144, 180

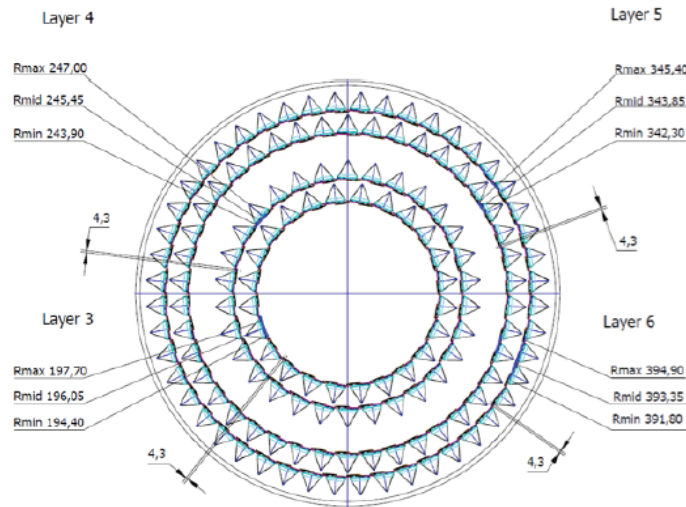
Material thickness:  $\leq 0.3\% X_0$  per layer

Stave weight  
~ 1.4 grams



# Concept Design of ALICE/ITS Module Assembly

## Outer Barrel



**Outer Barrel (OB):** 2 ML + 2 OL

Radial position (mm): 196, 245, 344, 393

Length in z (mm): 843, 1475

Nr. of staves: 24, 30, 42, 48

Nr. of half-staves/stave: 2

Nr. of modules/half-stave: 4 (ML), 7 (OL)

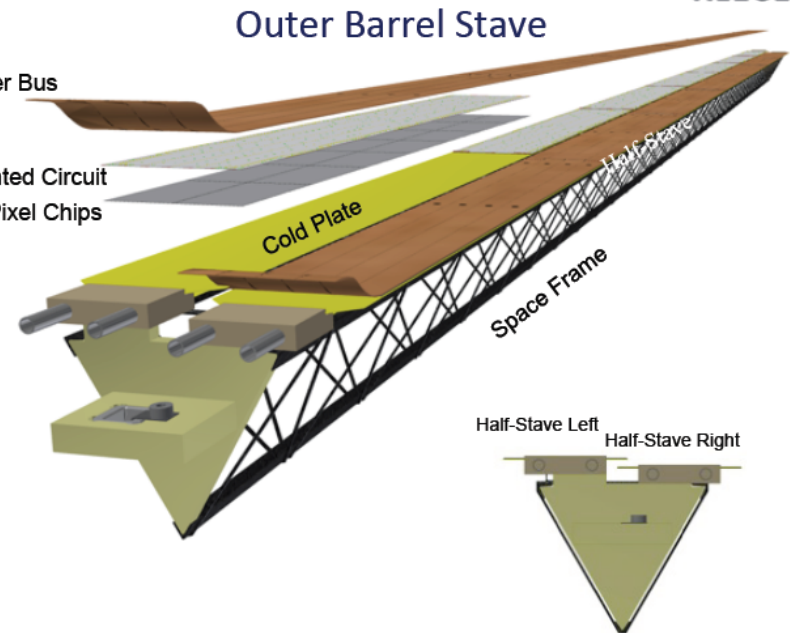
Nr. of chips/module: 14

Nr. of chips/layer: 2688, 3360, 8232, 9408

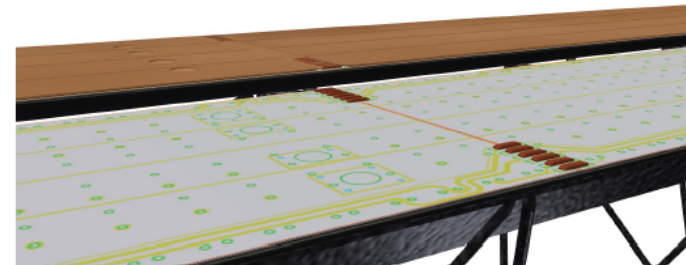
Material thickness:  $\sim 1\% X_0$  per layer

**Module:**

Flexible Printed Circuit  
2x7 Pixel Chips



Module to Module and  
Power Bus connections



## No. of modules and interconnections:

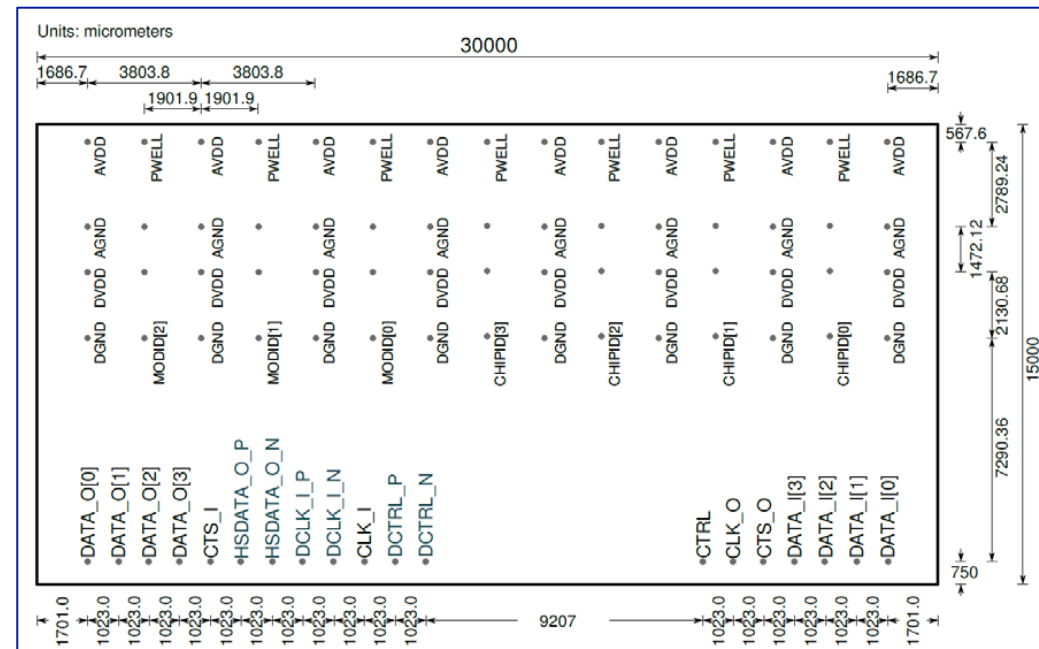
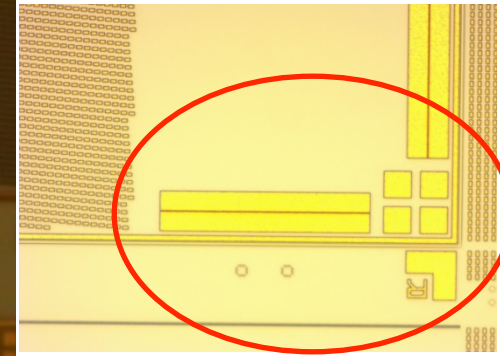
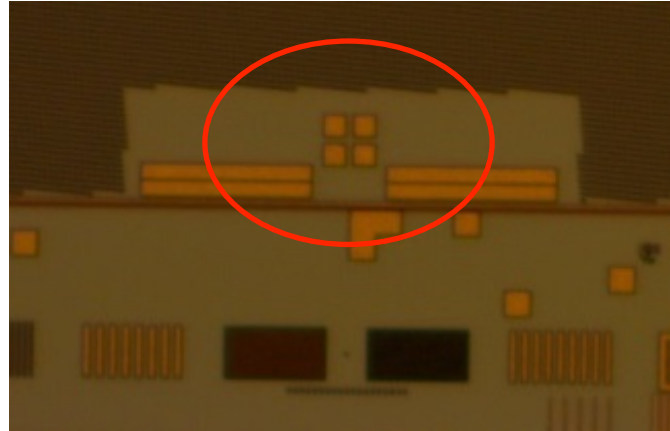
- Some redundancy in the quantity of modules to be produced is required, specifically 120% for the IB, 20% for the OB, resulting in a total **2136 Hybrid Integrated Circuits (HICs)**; more specifically:
  - IB: n. 106 “9-chips” HICs (954 chips to be soldered)
  - OB: n. 2030 “14-chips” HICs (28420 chips to be soldered)
- Considering ~ 80 pads/chip → ~ **2.4 M interconnections**



# Concept Design of ALICE/ITS Module Assembly

## Silicon chip main characteristics:

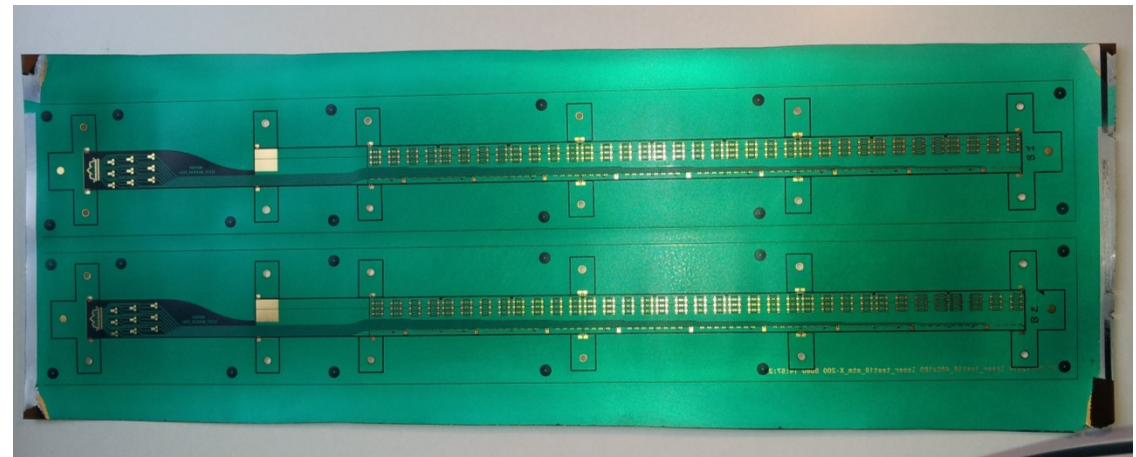
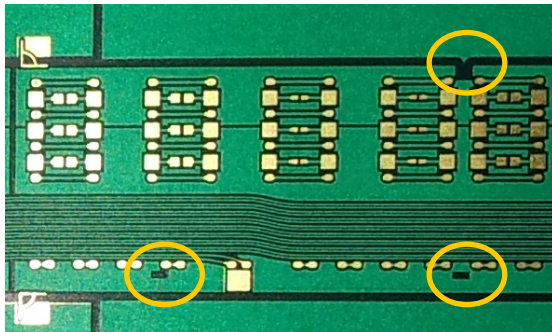
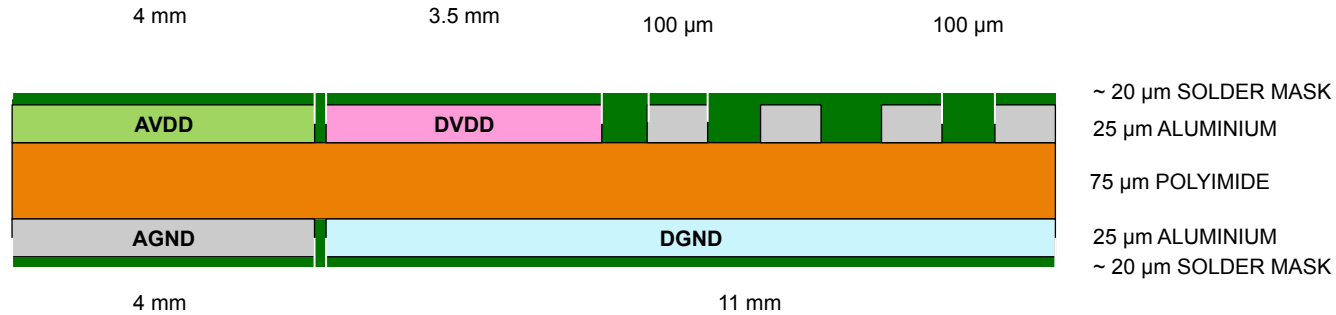
- 30x15 mm silicon chip, thinned to  $50 \pm 5 \mu\text{m}$ ; dicing tolerance  $-0/+30 \mu\text{m}$
- Contact pads are in aluminium, coated by Ni/Au,  $300 \mu\text{m}$  diameter
- Reference targets at the four corners and along the edges
- Chips warp  $\sim 0.5 \text{ mm}$



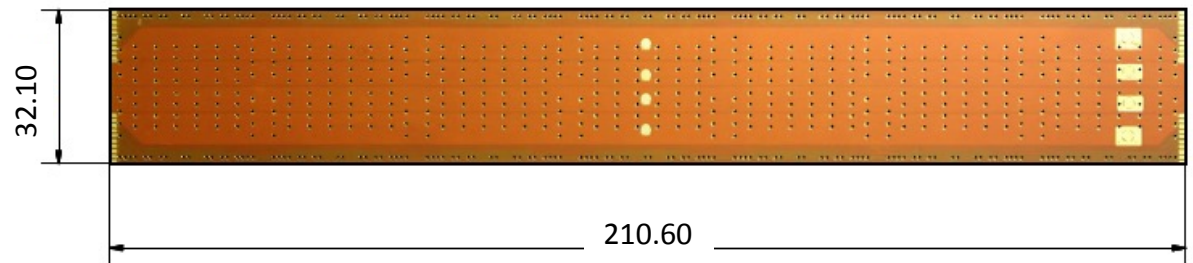
# Concept Design of ALICE/ITS Module Assembly

## FPC main characteristics:

- 3 layouts:
  - IB: 1x9 chips, Al
  - OB: 2x7 chips, Cu
  - MFT: 1x1, 1x2,..., 1x5 chips, Al
- Metallised vias of 220  $\mu\text{m}$  diameter
- Two openings of 1x1 and 1x0.4  $\text{mm}^2$ , respectively, to “see” chip targets



IB

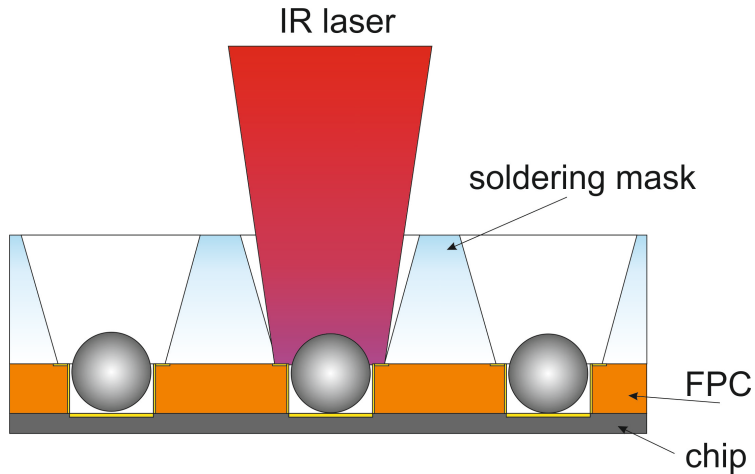


OB

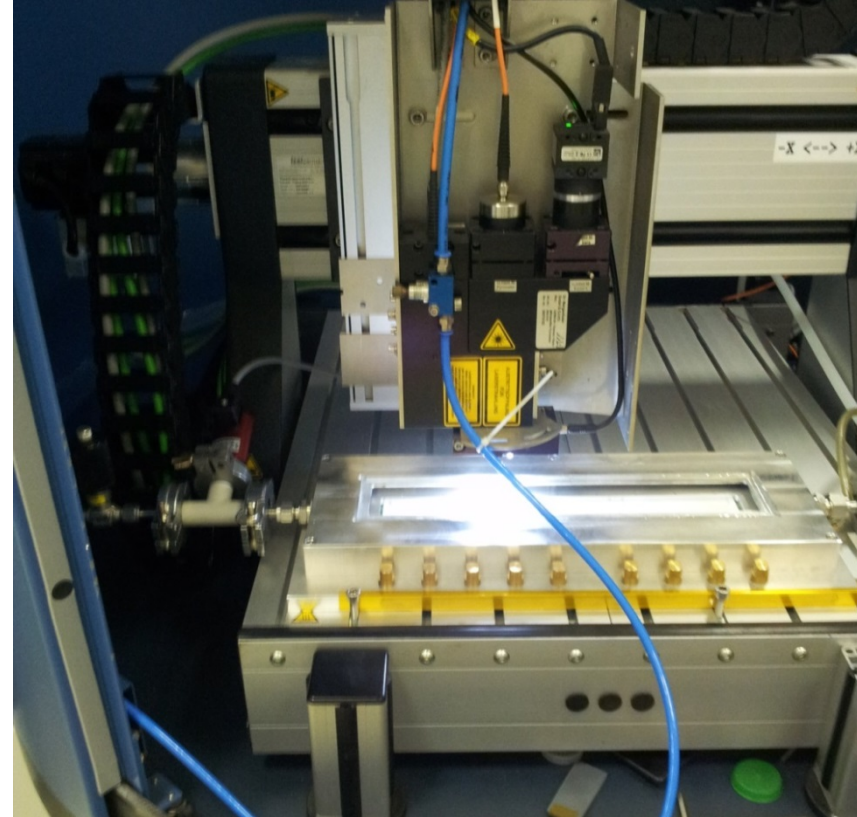


# Concept Design of ALICE/ITS Module Assembly

## Laser soldering main characteristics:



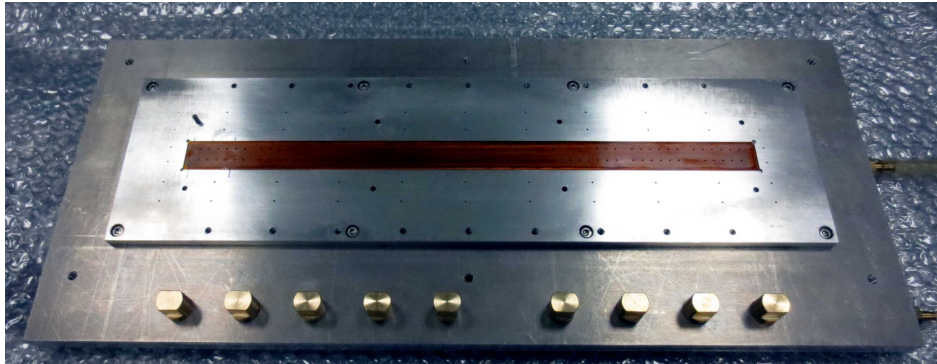
- Interconnection between FPC and chip by fluxless laser soldering of 200  $\mu\text{m}$  diameter Sn/Ag(96.5/3.5) balls (227  $^{\circ}\text{C}$  melting T) in vacuum ( $\leq 10^{-1}$  mbar)
- IR diode laser, 976 nm, 25 W, 50 mm focal length, 0.25 mm beam spot size
- Laser power modulated by pyrometer (LASCON<sup>®</sup> system supplied by Dr. Mergenthaler GMBH & CO), programmable T profile ensures precise limitation of heating
- Soldering mask (in Macor<sup>®</sup> or Rubalit<sup>®</sup>) used to push FPC on chip and guide soldering balls inside FPC vias



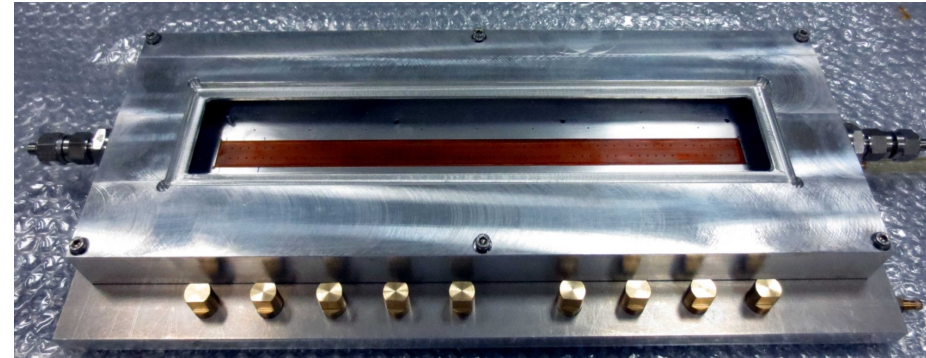
# Concept Design of ALICE/ITS Module Assembly

## Tooling for the module assembly: IB work table

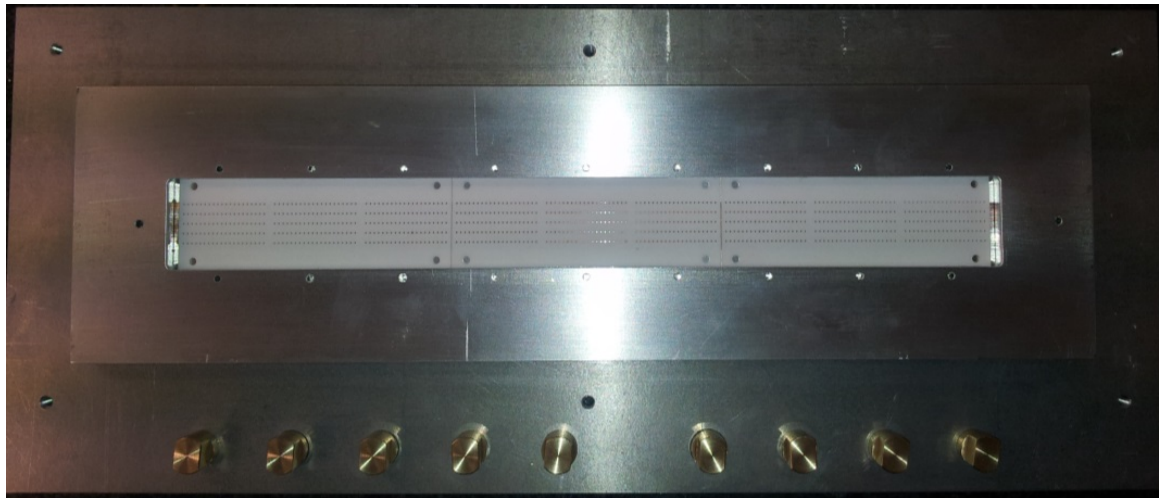
**The chips vacuum chuck**



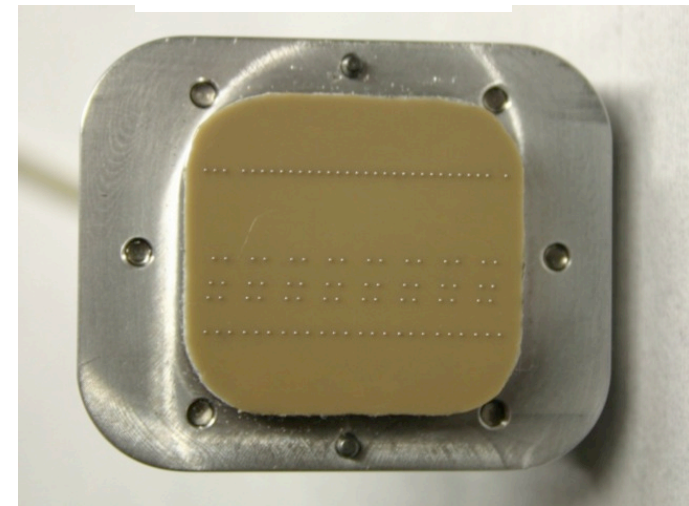
**Vacuum lid with quartz window**



**The soldering mask**



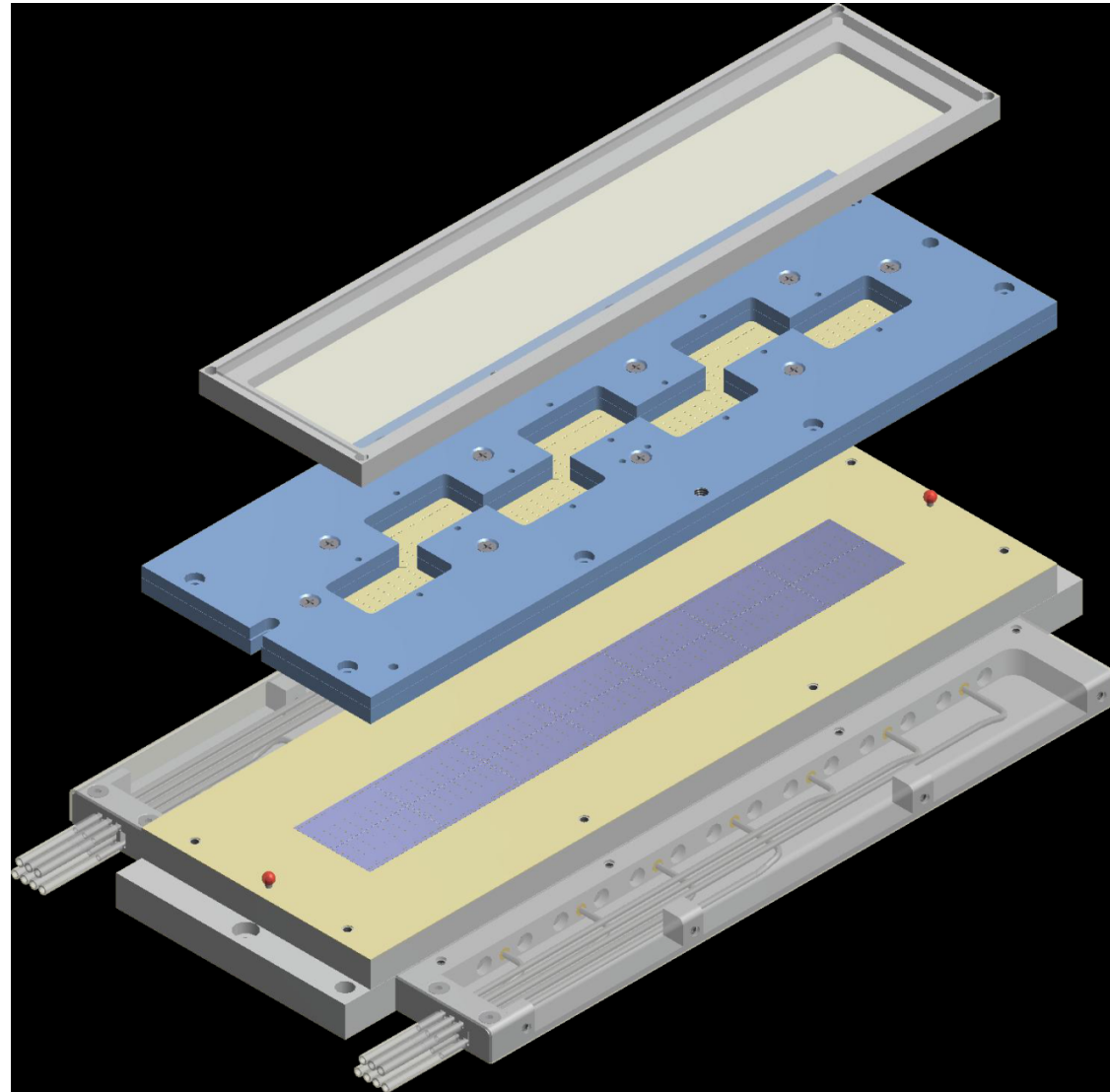
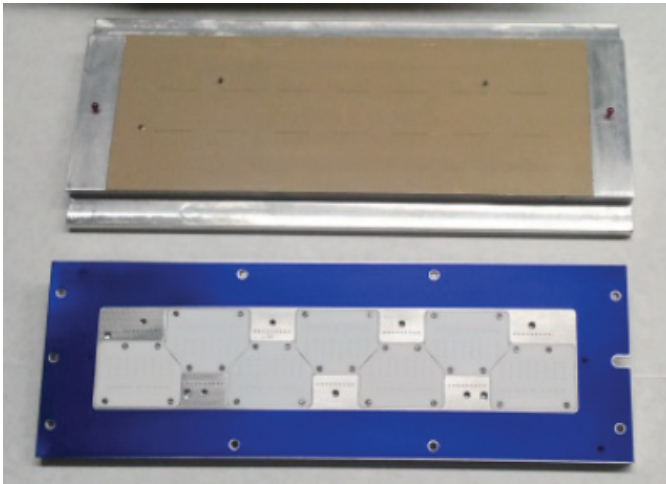
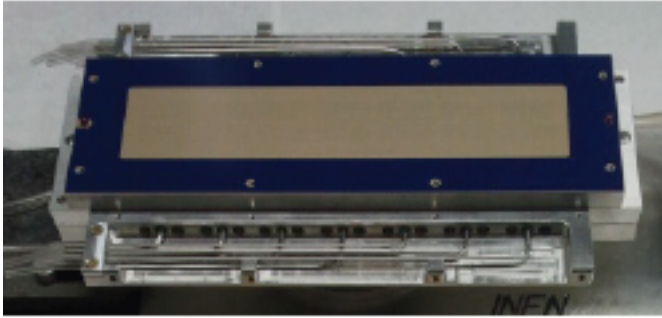
**Ball transfer tool**





# Concept Design of ALICE/ITS Module Assembly

## Tooling for the module assembly: OB work table



# Concept Design of ALICE/ITS Module Assembly

## Accuracy required to the module assembly:

- Presently, final accuracy of FPC hole position not yet known:
  - IB: Al FPC  $\sim 50 \mu\text{m}$  (hope to improve it)
  - OB: Cu FPC  $\sim 20 \mu\text{m}$
- The  $300 \mu\text{m}$  pad can compensate hole position variations up to  $\pm 40 \mu\text{m}$
- The  $100 \mu\text{m}$  gap between chips seal ring, with the present dicing accuracy, translates in a physical gap between chip edges of  $\sim 40\text{-}50 \mu\text{m}$  (if needed it could be increased)
- A chip placement accuracy of  $\pm 5 \mu\text{m}$  is a very tight and conservative requirement to prevent issues related to FPC/chip alignment

## Key aspects of the module assembly:

- The amount of modules and the time available require a distributed production over 6 sites (Bari/Italy, CERN, Liverpool/UK, Pusan/Korea, Strasbourg/France, **Wuhan/China**).
- Usage of same procedure and system is necessary to ensure homogenous production
- To simplify/shorten the assembly procedure, chips are placed in nominal positions and FPC is overlapped using nominal pinholes

## Baseline module assembly system:

- Semi-automatic placement of chips on flat vacuum chuck: operator moves chips from pallet using a console, placement assisted by vision system, inter-chip gap (from seal-ring) of 100  $\mu\text{m}$ , required position tolerance of  $\pm 5 \mu\text{m}$  at  $3\sigma$  with respect to reference targets on assembly table
- Stack of FPC + soldering mask placed manually by operator on top of chips
- Distribution of 200  $\mu\text{m}$  soldering balls inside mask holes by operator
- Mounting of lid with quartz window and start of vacuum pump by operator
- Automatic laser soldering of each interconnection; X,Y positioning accuracy:  $\pm 30 \mu\text{m}$ . Three different modes of operations:
  - fully manual by console; this mode is used for testing purposes and laser beam focusing optimization;
  - programmable in X,Y, providing coordinates either as keyboard input or from a file;
  - fully automated, centred in FPC holes recognized by the vision system.

# Concept Design of ALICE/ITS Module Assembly

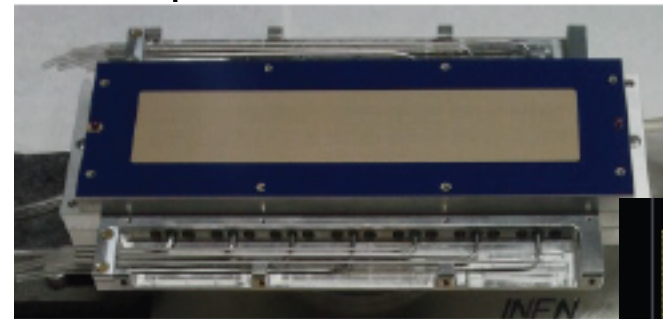
## Module assembly procedures:

### 1. Chip visual inspection – dimensions, warp, integrity, cleanness



### 2. Chip placement/alignment – pick up from the chip pallet and place above a vacuum chuck in nominal position w.r.t. reference point

- 9 (14) chips one by one
- Use reference markers on chip surface and vacuum chuck
- Gap between adjacent chips:
  - ☑ 100 um between nominal edge
  - ☑ 200 um between center of cross reference makers



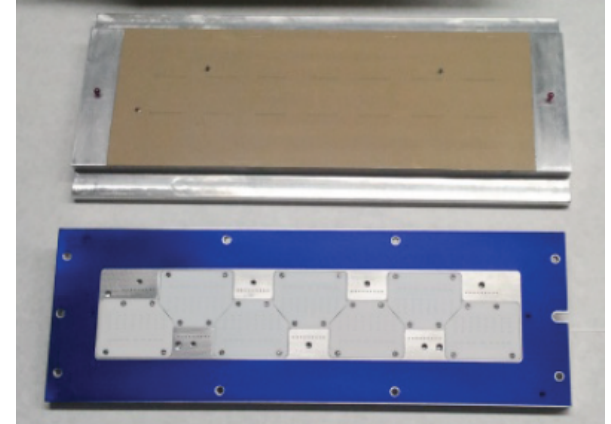


# Concept Design of ALICE/ITS Module Assembly

## Module assembly procedures:

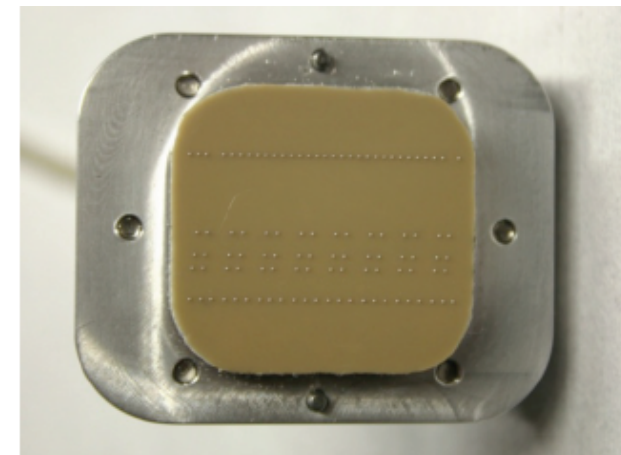
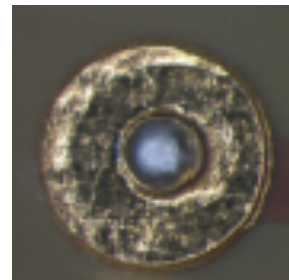
**3. FPC placement/alignment** – placement above the chips array in nominal position using a jig embedding a soldering mask.

- Use locating pinholes and ruby spheres
- The soldering mask is a ceramic plate with 0.5 mm holes corresponding to the FPC vias
- The jig gently press the FPC against the pixel chips to minimize the gap between them



**4. Soldering balls placement** – fill the soldering mask holes with the soldering balls using the ball transfer tool

- The soldering mask guides the soldering balls into the FPC vias
- One chip at a time, use pinholes for alignment
- Visual inspection to ensure each hole is filled one and only one soldering ball

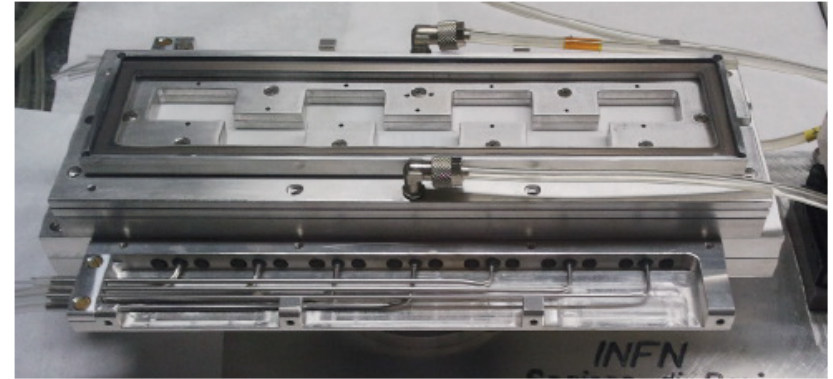


# Concept Design of ALICE/ITS Module Assembly

## Module assembly procedures:

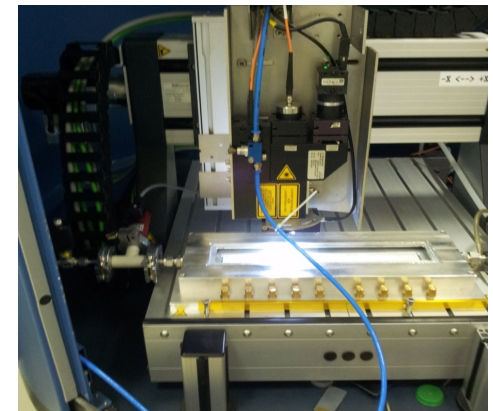
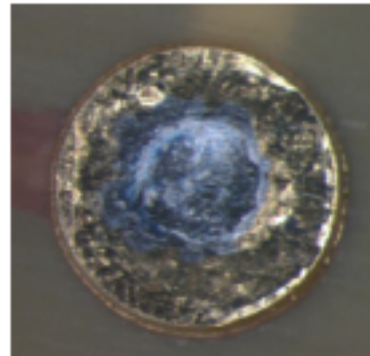
**5. Soldering readiness** – install the vacuum tight lid equipped with the quartz window above the pixel chips, FPC and soldering mask stack-up

- Start vacuum pump to empty the soldering volume till ready for laser soldering
- Pressure of the chip vacuum chuck always smaller than the soldering volume



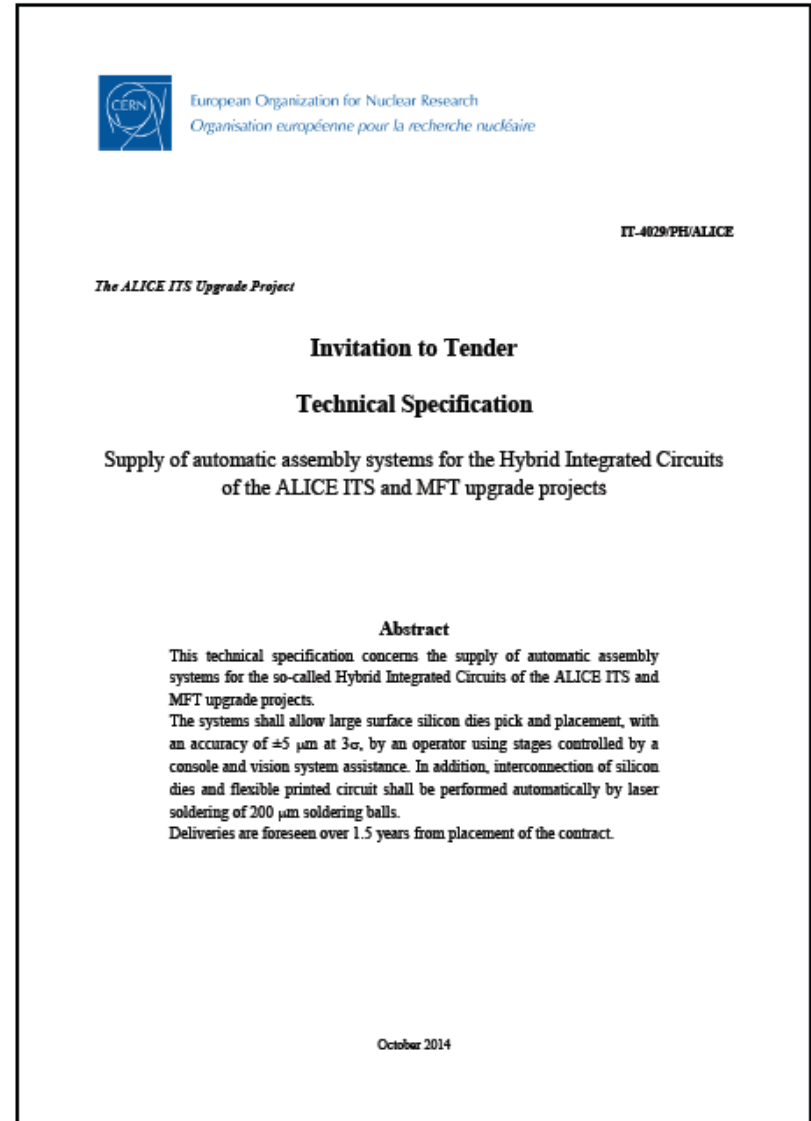
**6. Laser soldering** – shoot laser through the quartz window onto each soldering balls in sequence to melt them and establish the connection between FPC and chip

- Visual checks of soldering joints



## OB module construction:

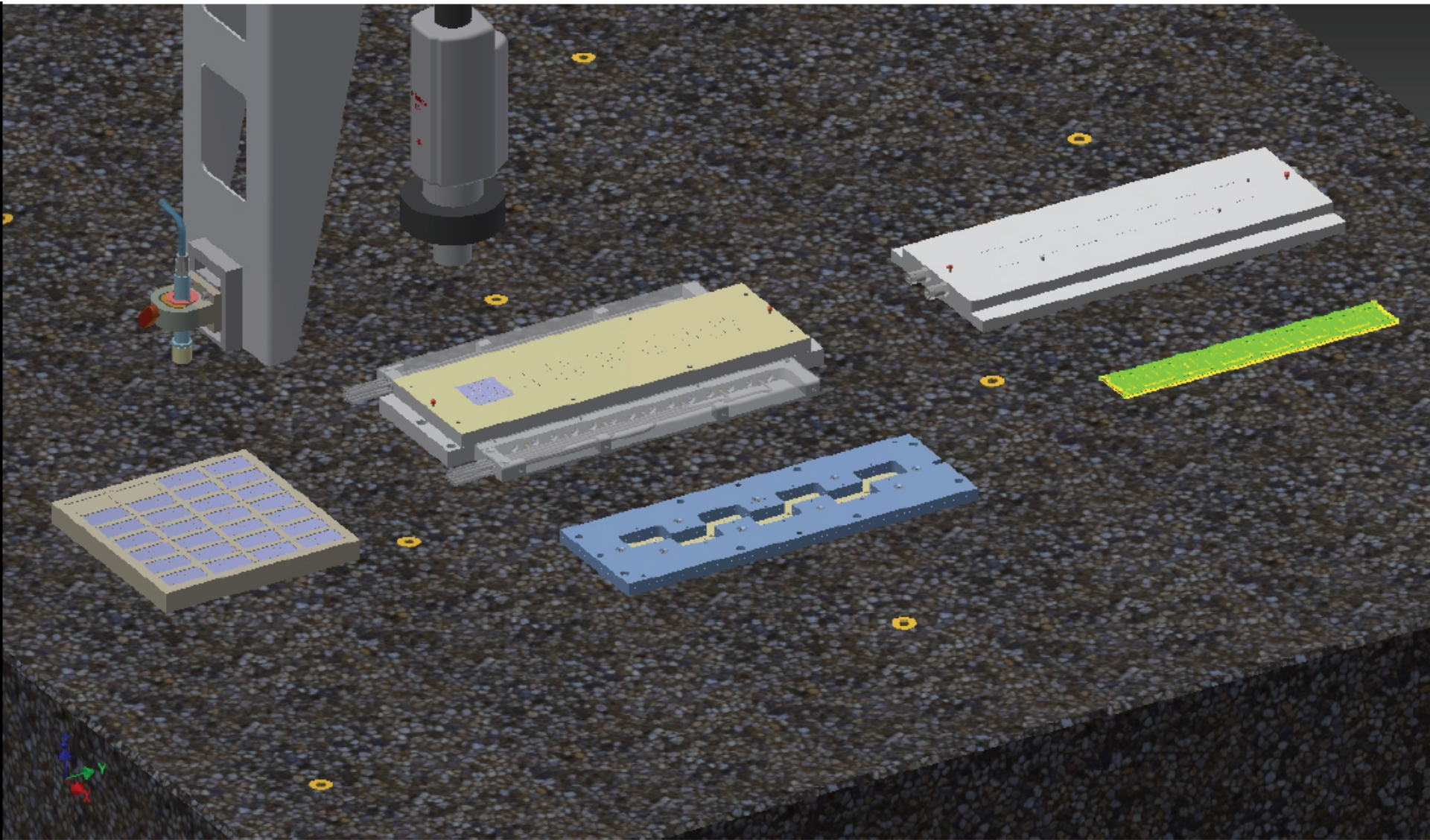
- Procurement of the automatic assembly systems is centrally managed by the project with a tendering launched from CERN.





# Concept Design of ALICE/ITS Module Assembly

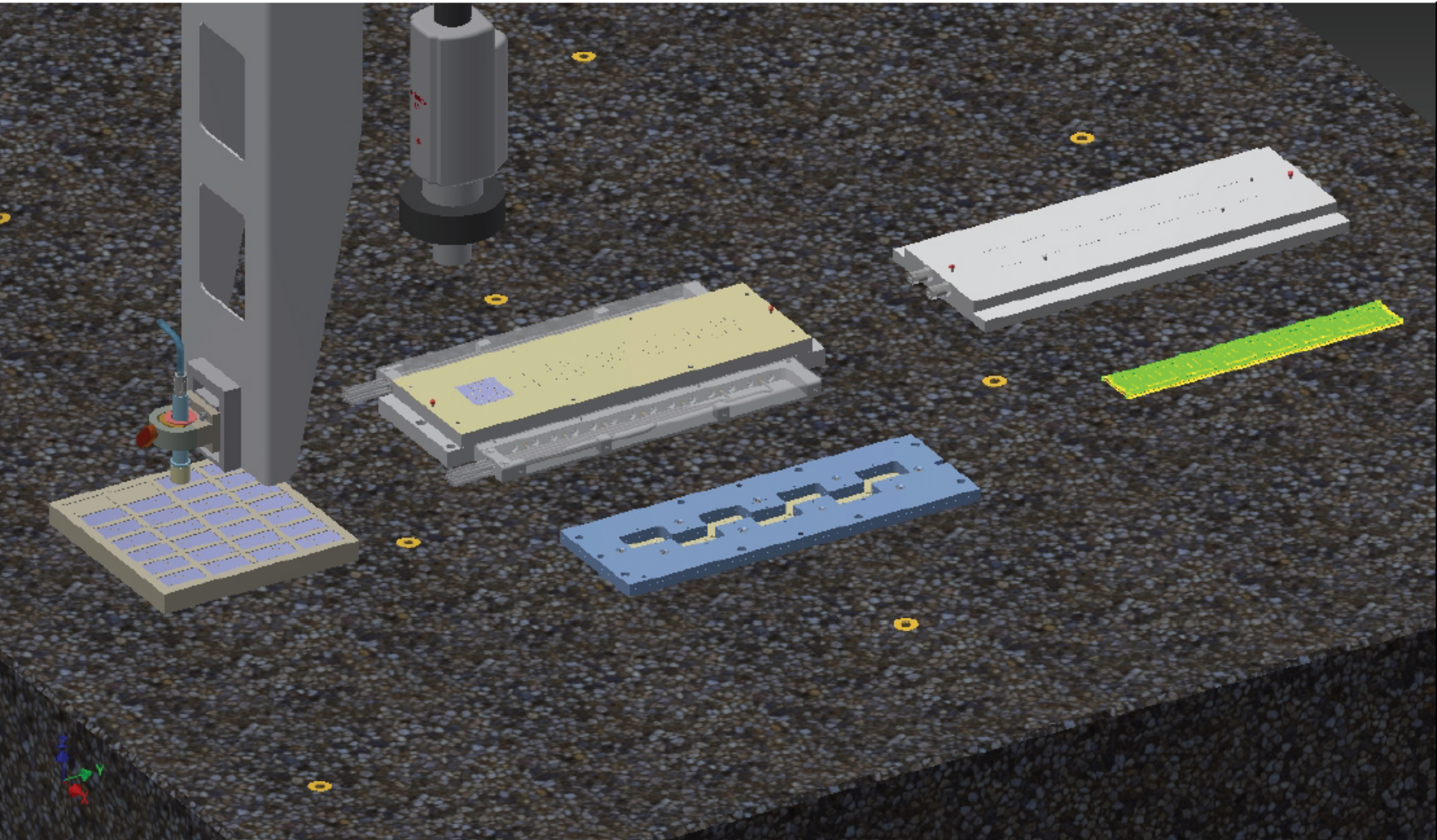
Assembly cartoon with automatic module assembly machine:





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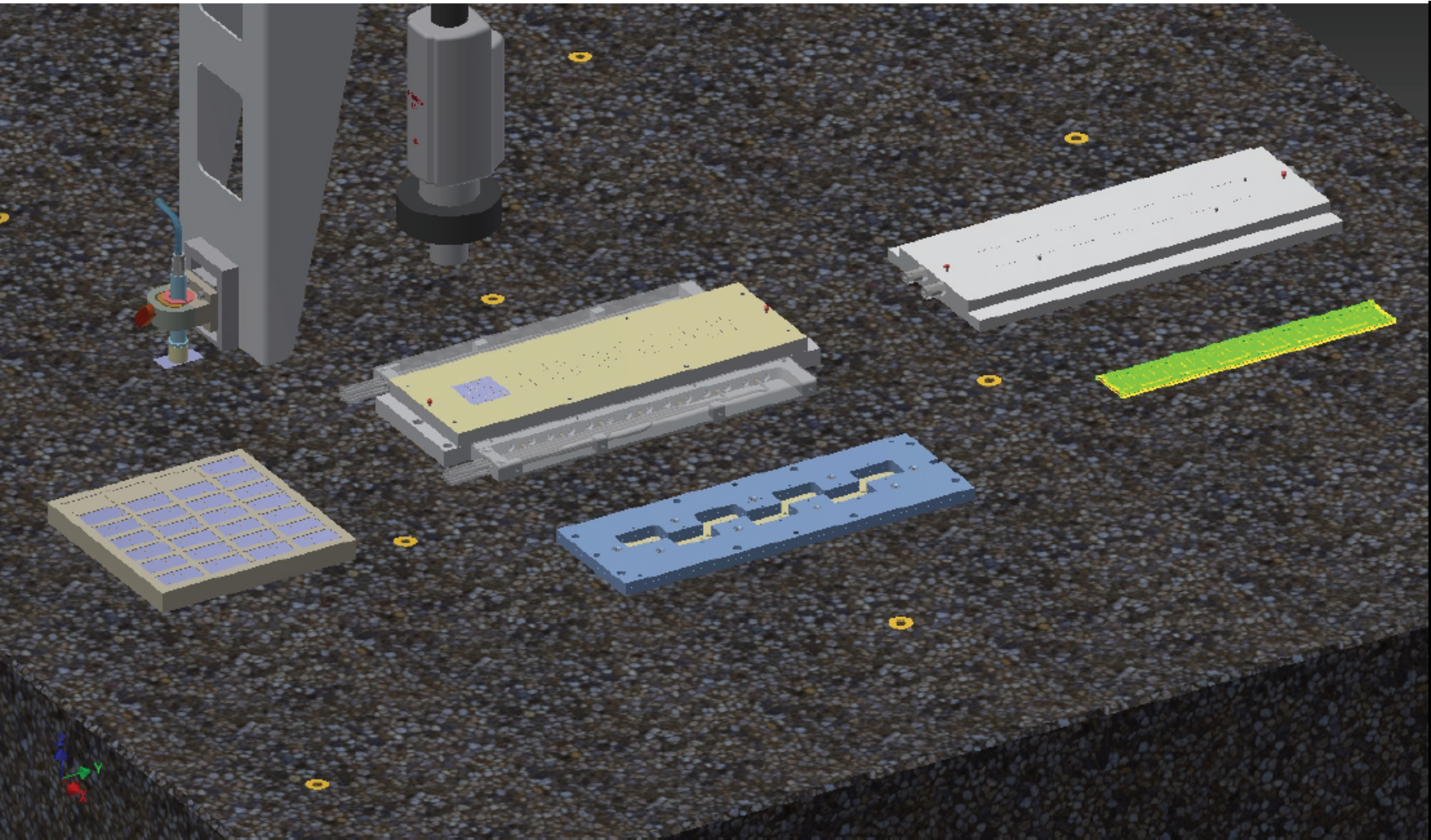
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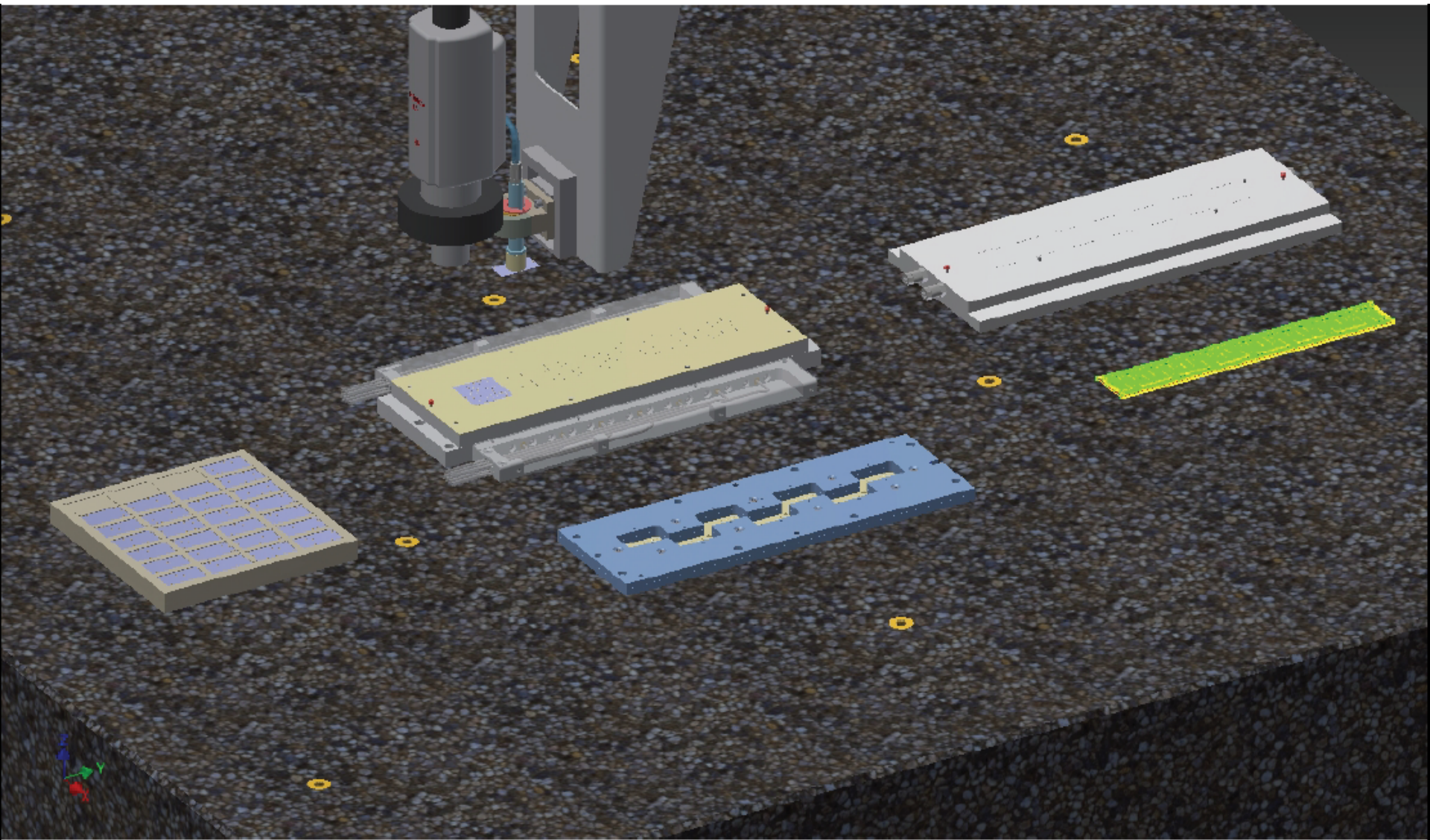
Assembly cartoon with automatic module assembly machine:





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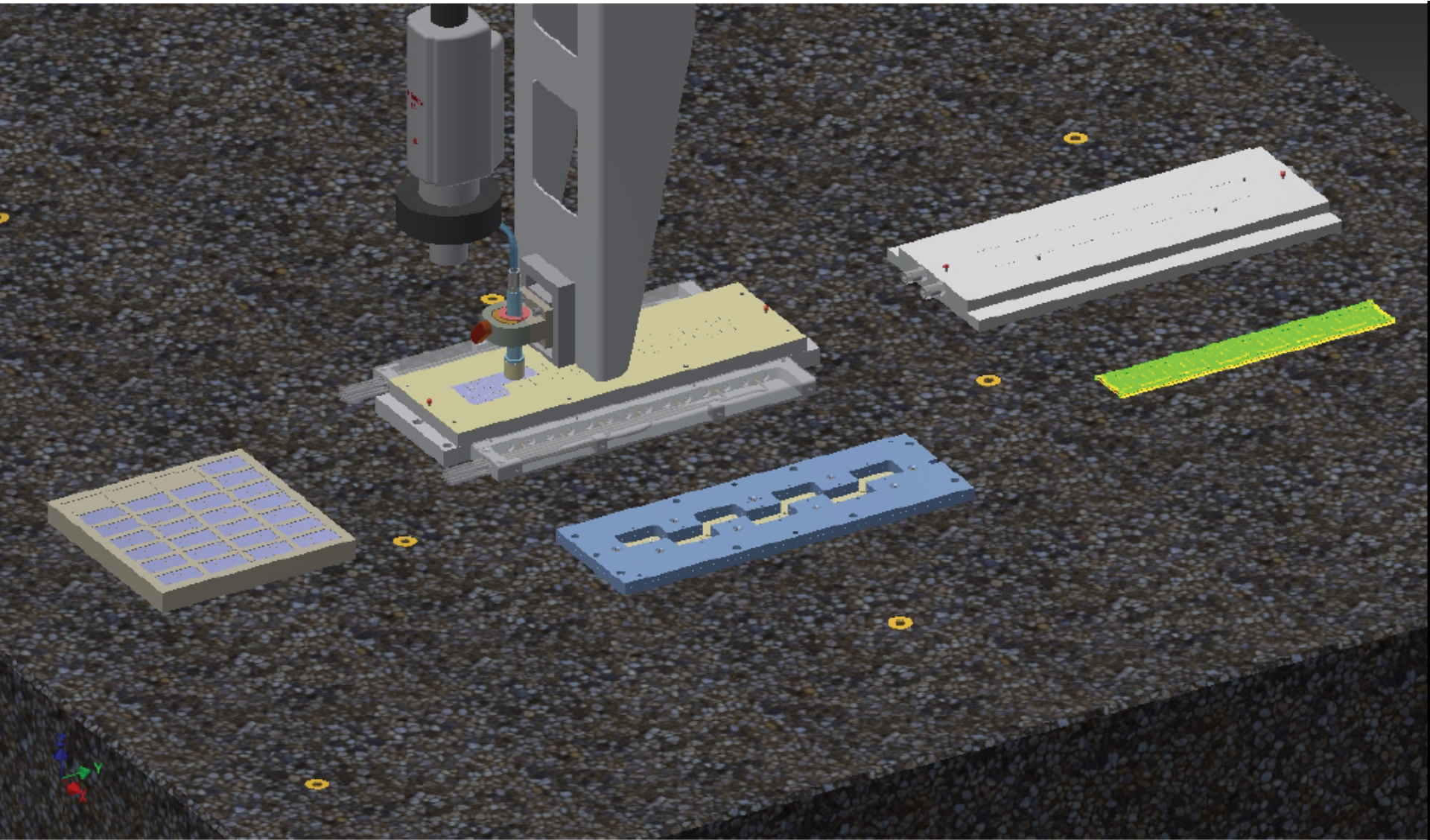
Assembly cartoon with automatic module assembly machine:





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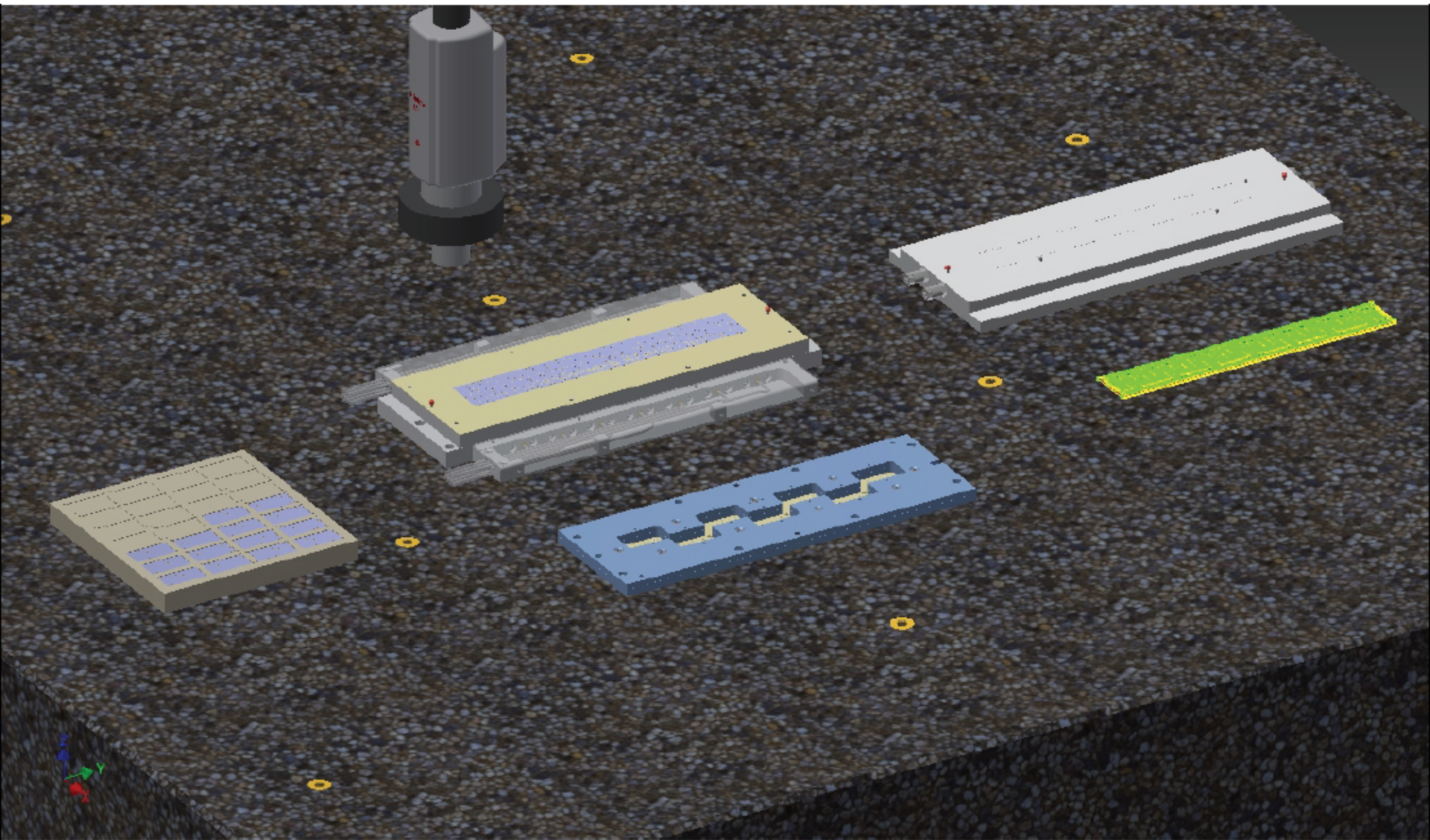
Assembly cartoon with automatic module assembly machine:





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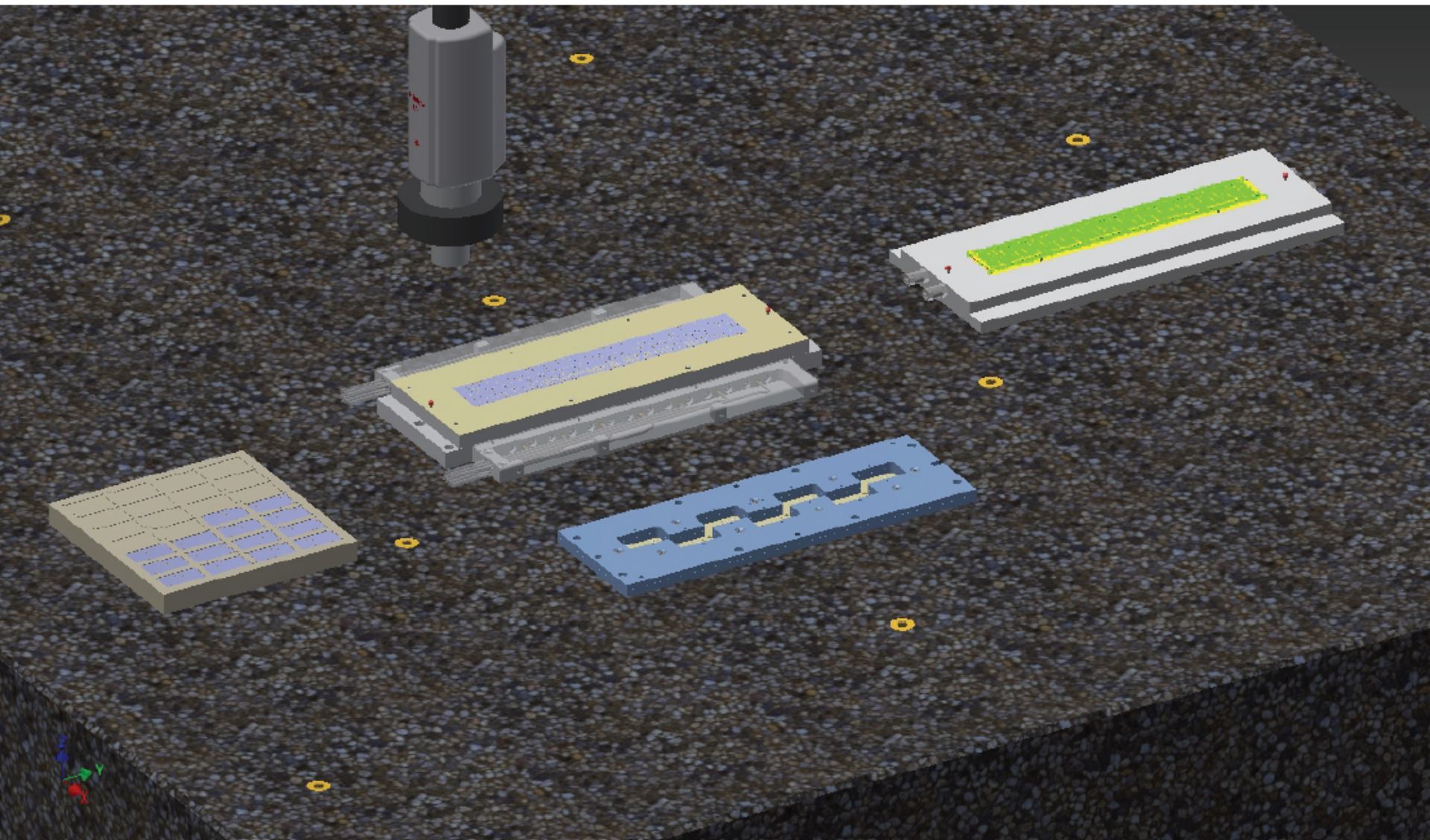
Assembly cartoon with automatic module assembly machine:





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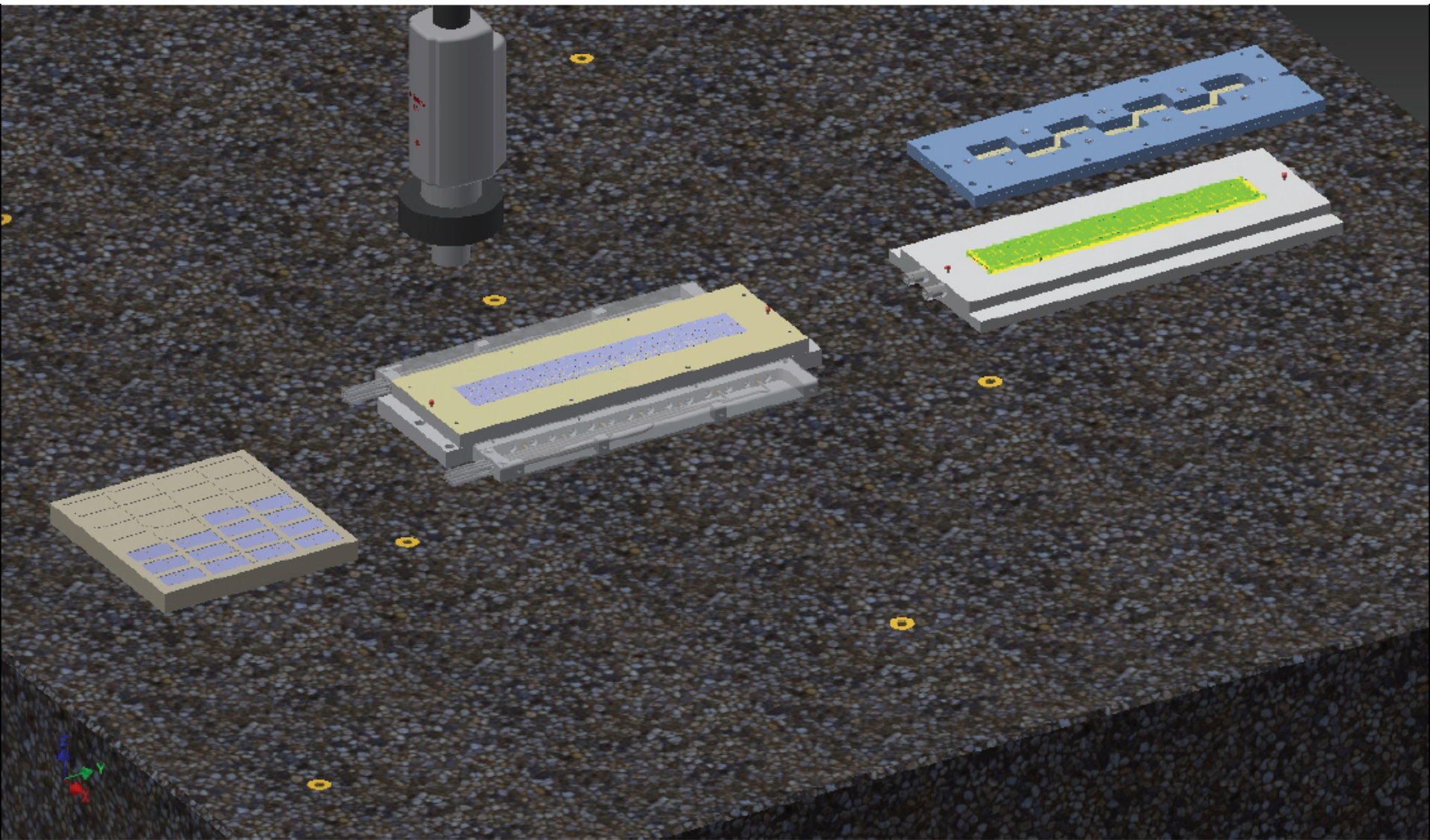
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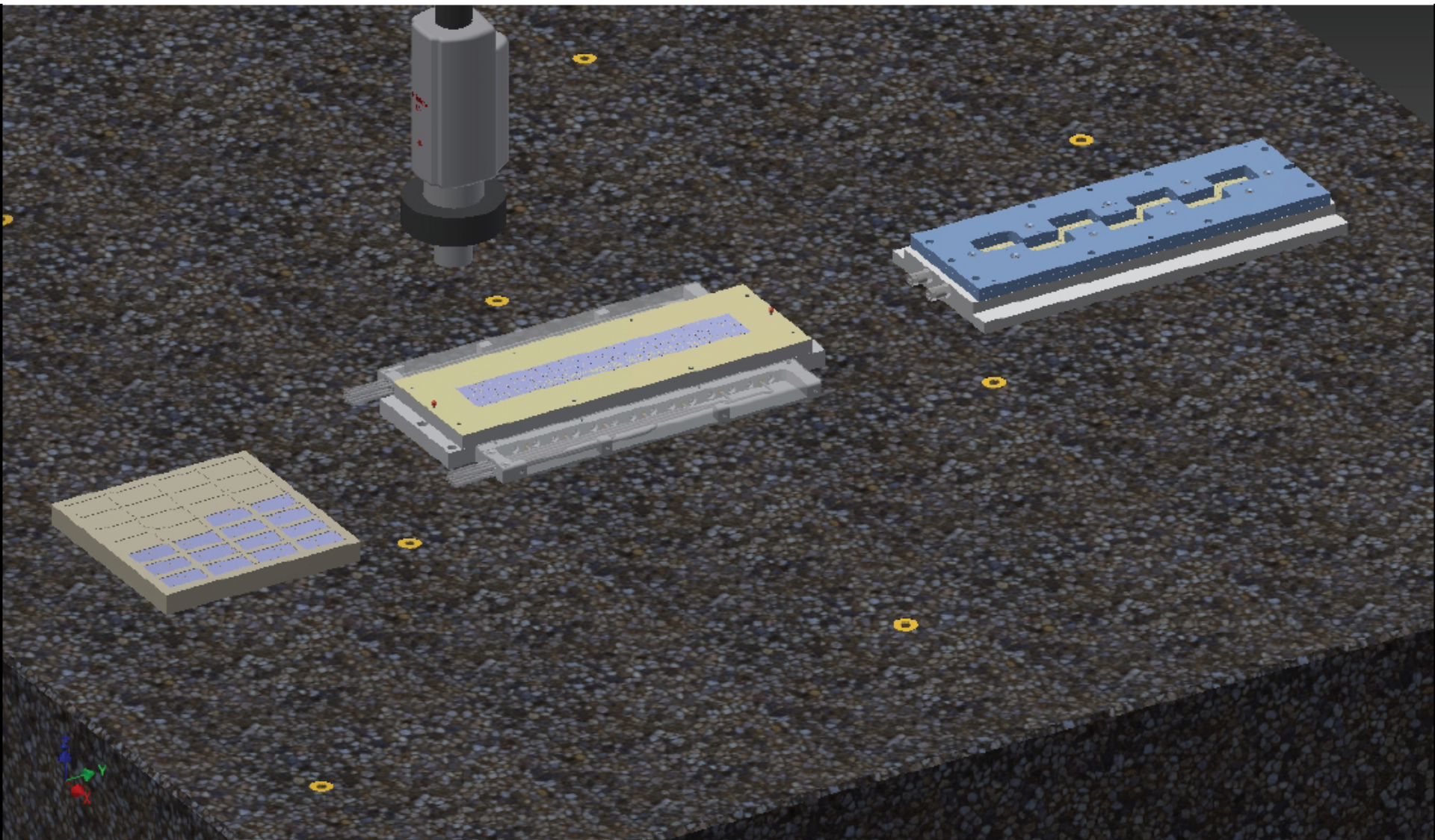
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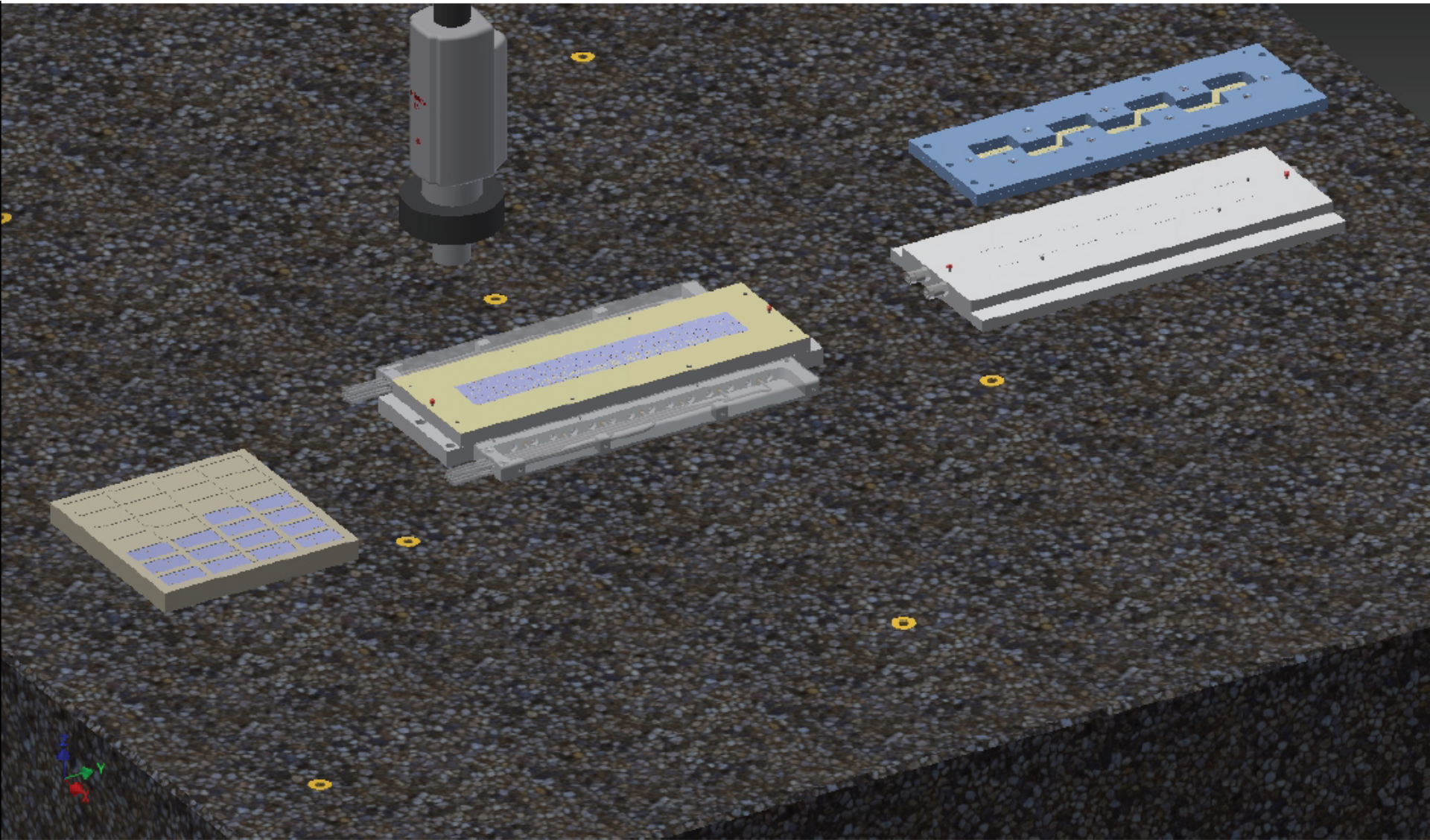
Assembly cartoon with automatic module assembly machine:





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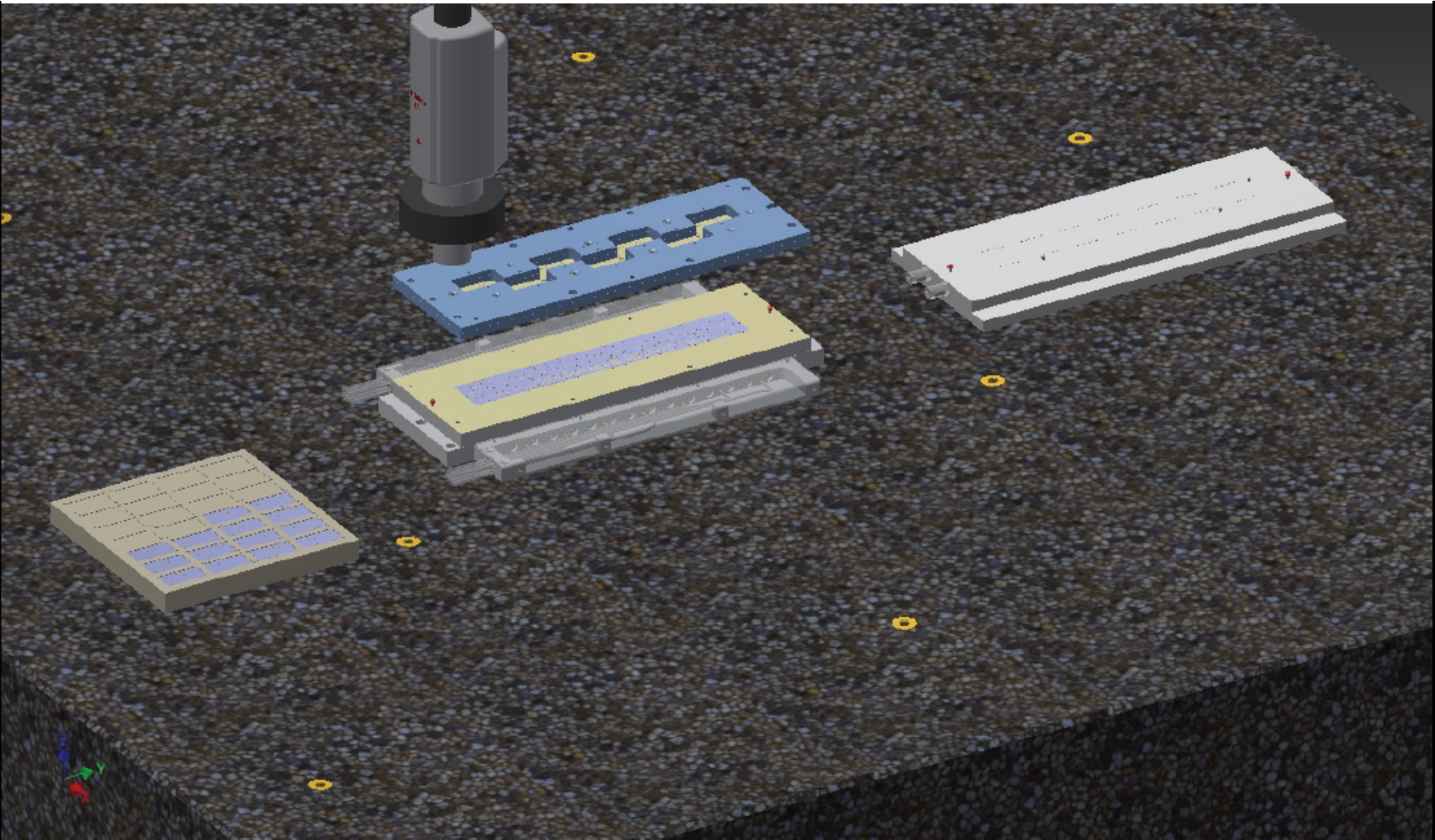
Assembly cartoon with automatic module assembly machine:





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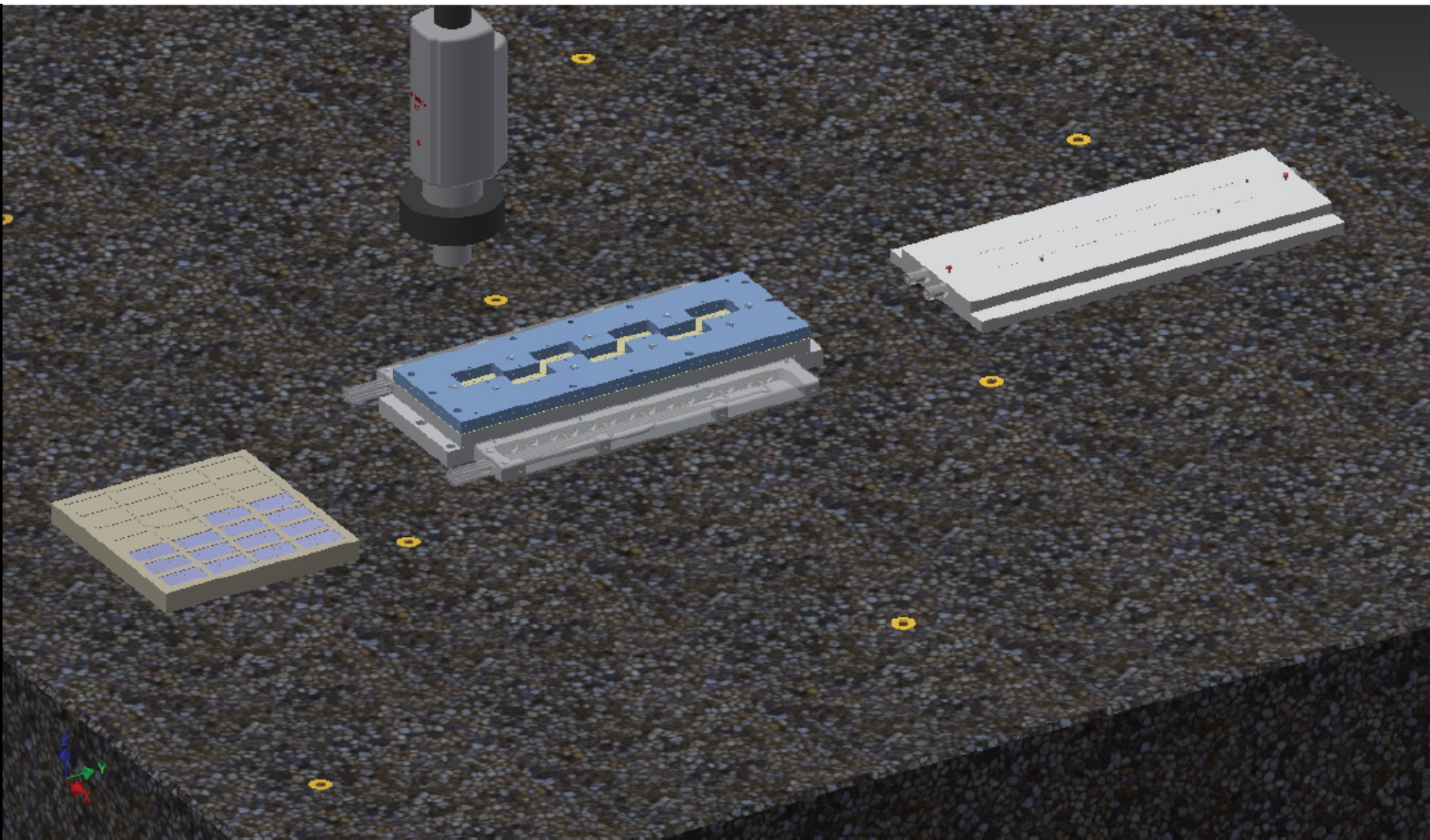
Assembly cartoon with automatic module assembly machine:





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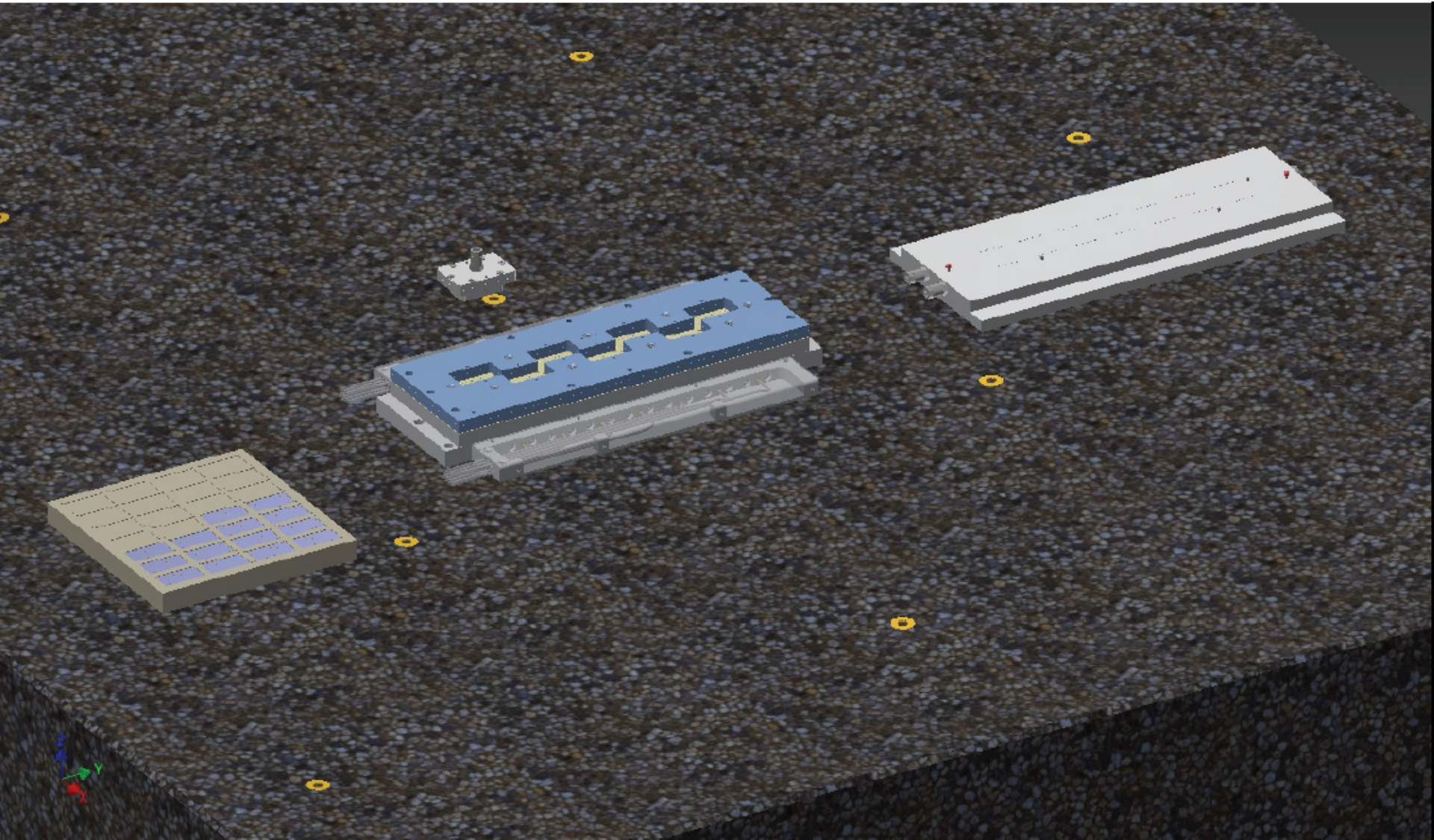
Assembly cartoon with automatic module assembly machine:





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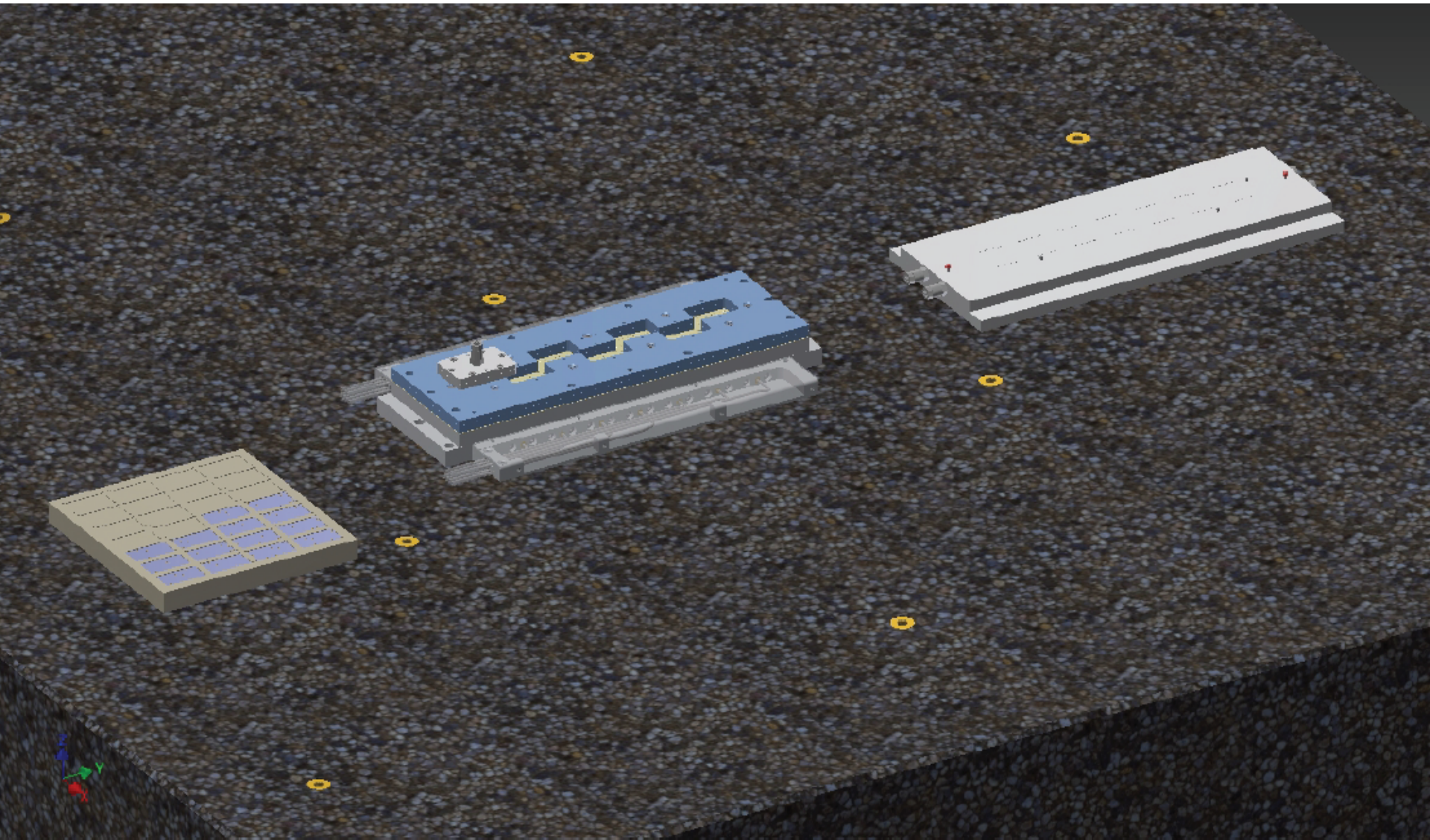
Assembly cartoon with automatic module assembly machine:





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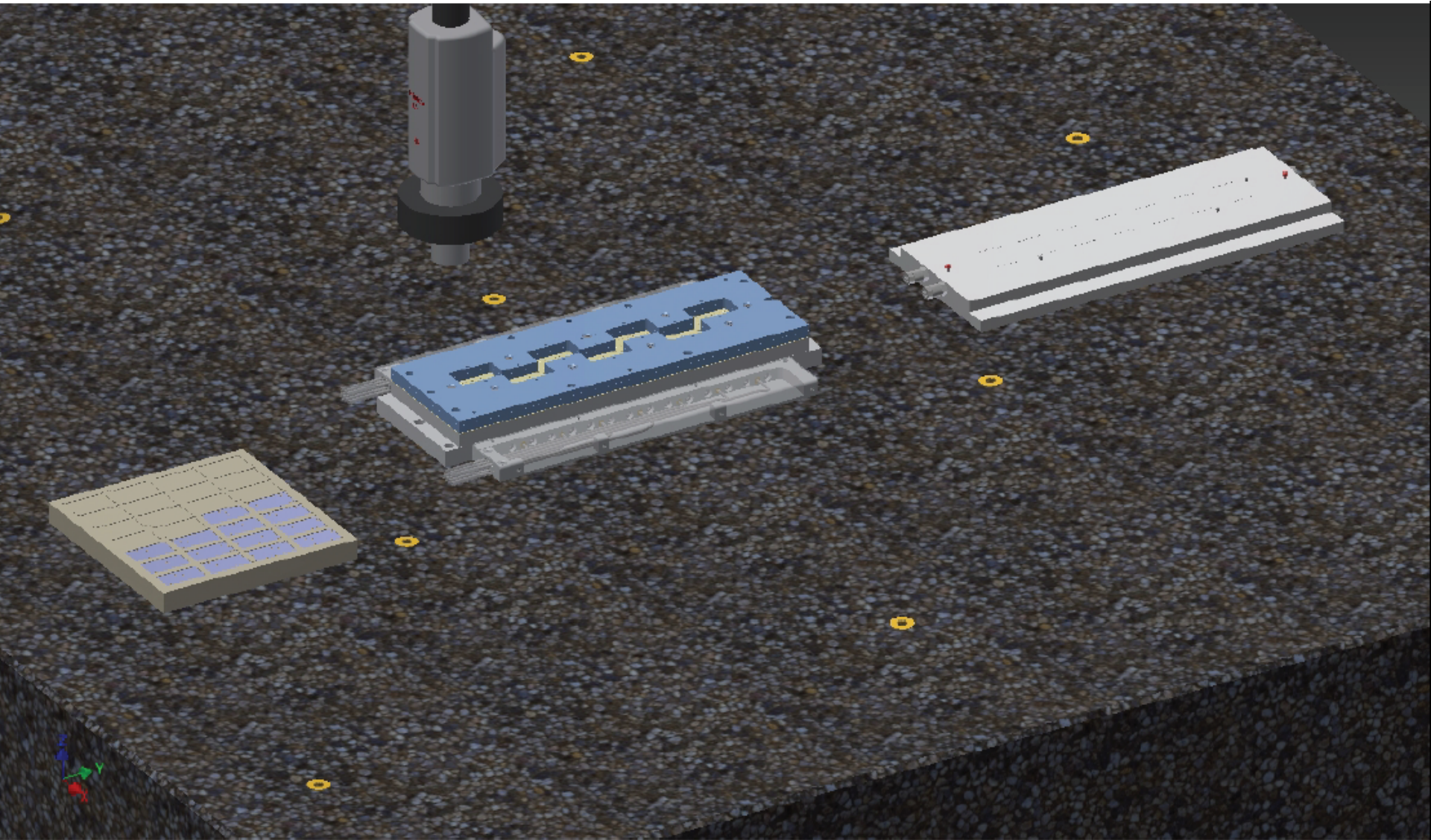
Assembly cartoon with automatic module assembly machine:





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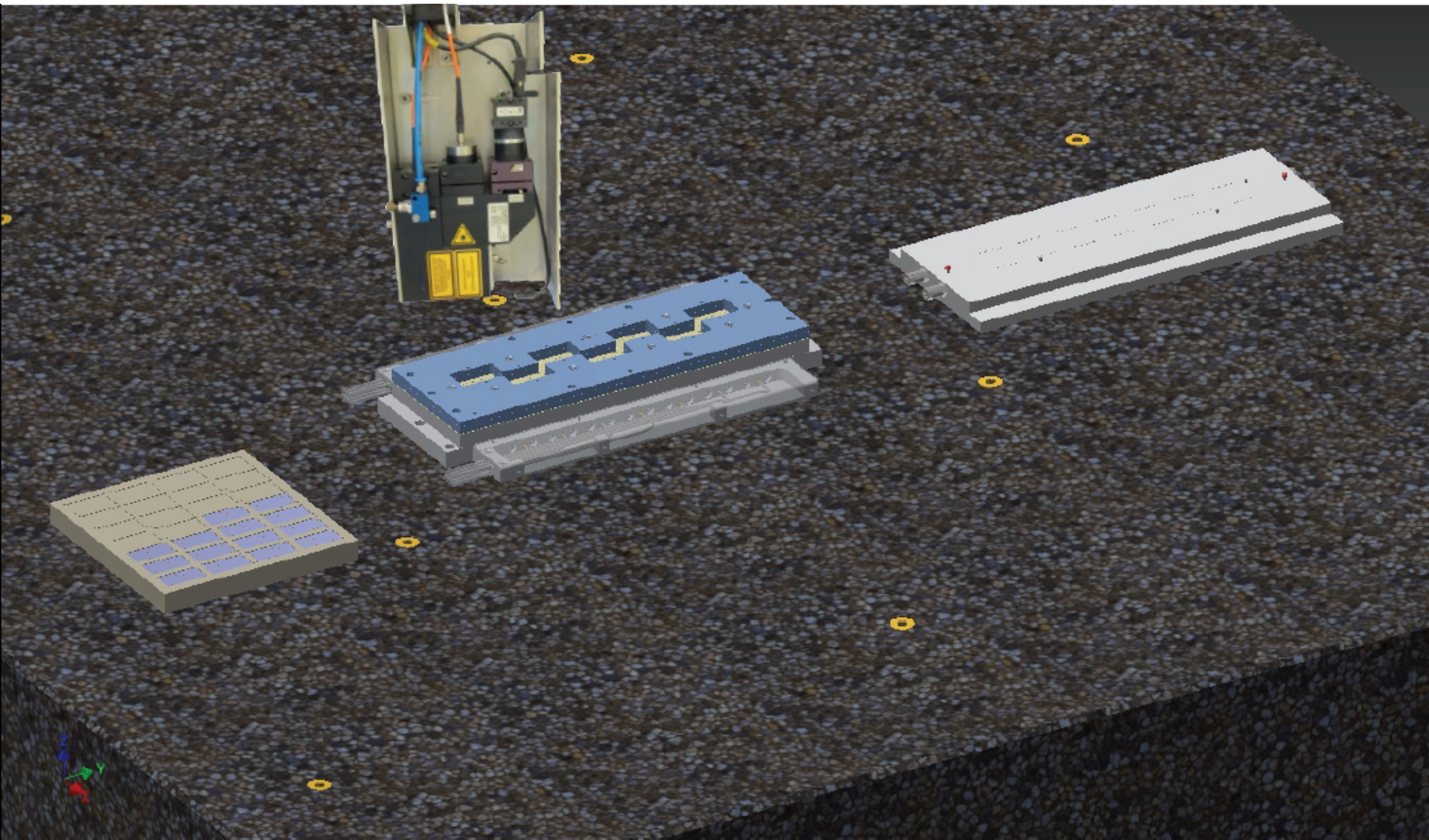
Assembly cartoon with automatic module assembly machine:





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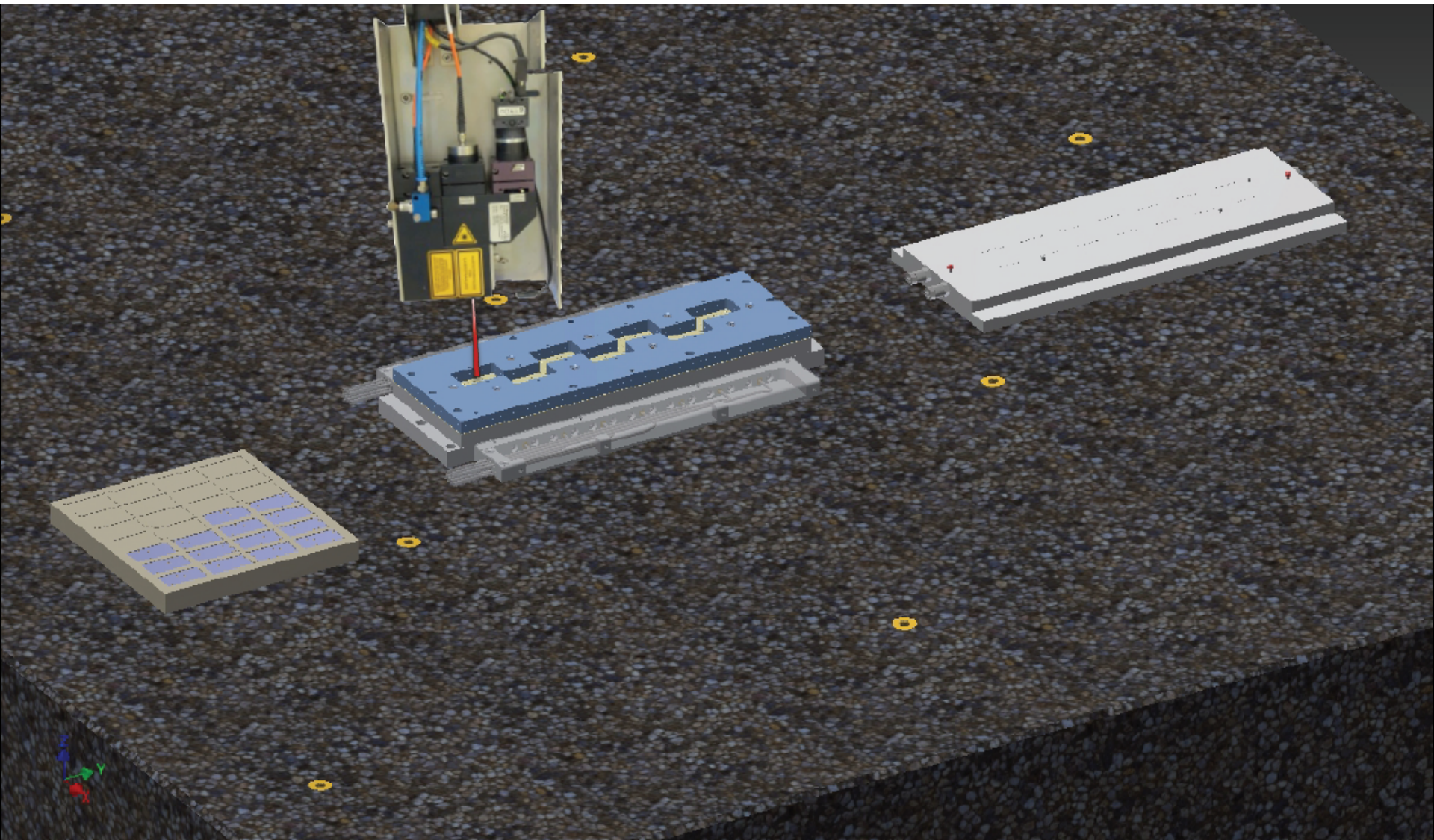
Assembly cartoon with automatic module assembly machine:





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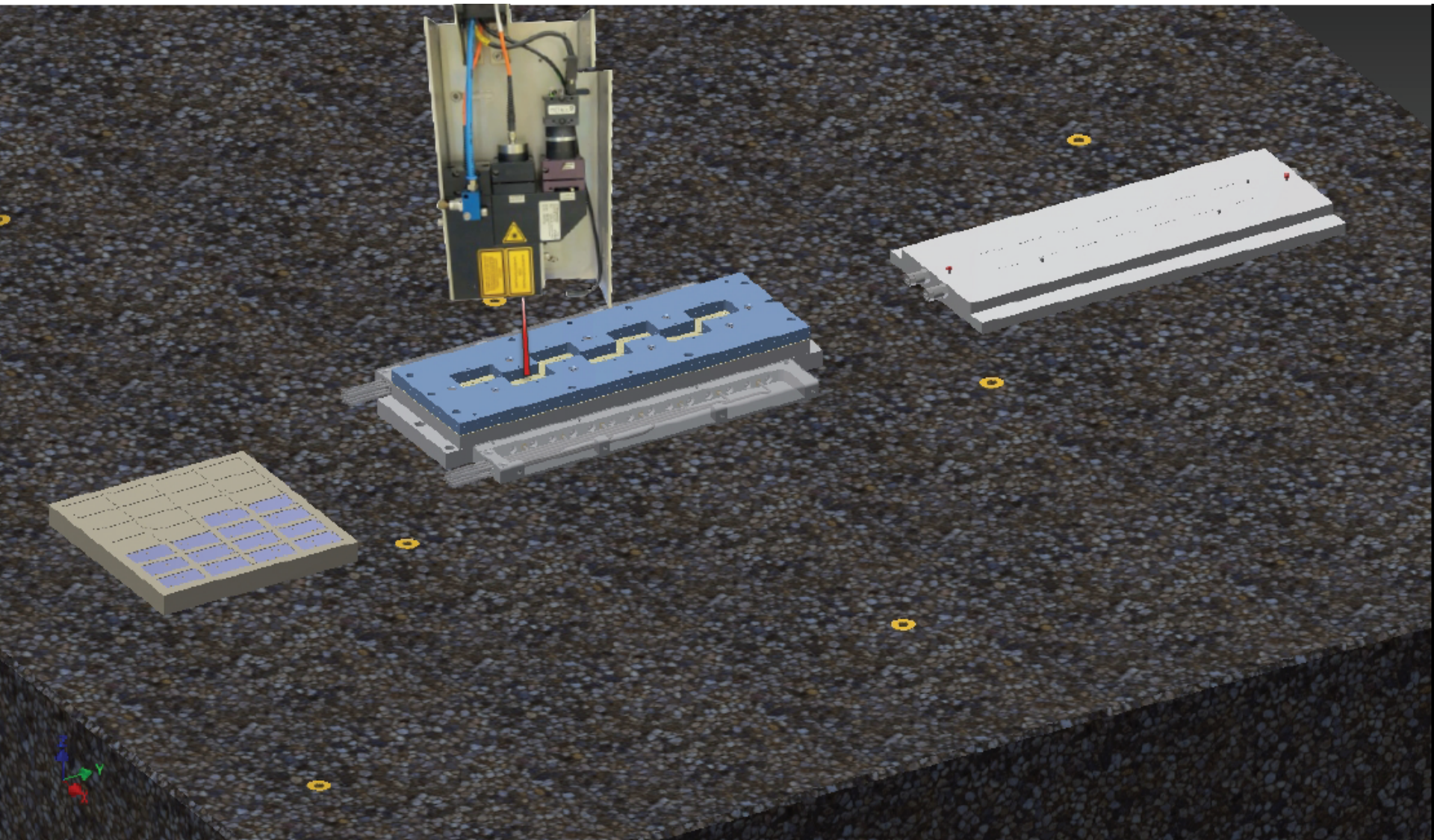
Assembly cartoon with automatic module assembly machine:





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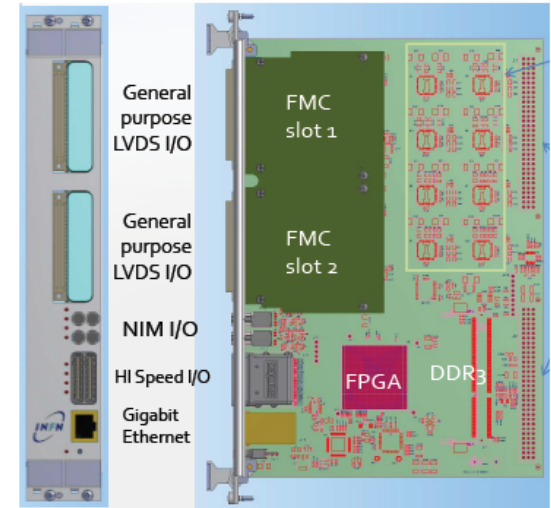
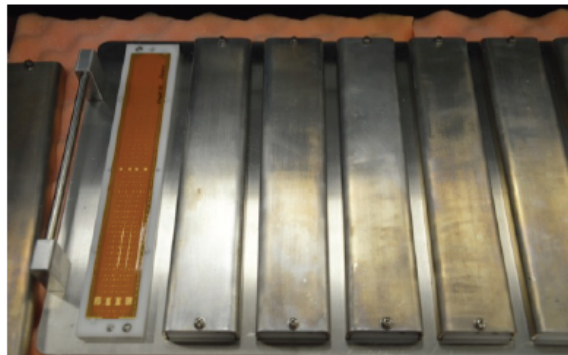
Assembly cartoon with automatic module assembly machine:



# Concept Design of ALICE/ITS Module Assembly

## Module test and shipment:

1. **Chips position** - measurements of chips position in the module with respect to reference markers, which will remain visible throughout the following construction and integration operations
2. **Module characterization** - functional validation of modules according to a defined protocol
  - Test System developed by Bari group
3. **Module transport** - shipment of qualified modules to the Stave Construction Centers
  - Liverpool, LBNL, Turin and LNF, NIKHEF



V. Manzari - ALICE ITS upgrade, MFT and O<sup>2</sup> Asian Workshop 2014 @ Pusan -15 Dec '14



## Construction site preparation:

- ✓ ~40 m<sup>2</sup> of a clean room class 100000
- ✓ Compressed air and nitrogen supplies
- ✓ Automatic assembly system
- ✓ Optical microscope for visual inspection, equipped with with image acquisition system
- ✓ Test bench equipped with readout and control system, cooling system and power supply systems
- ✓ Radioactive sources (typically <sup>90</sup>Sr, activity ~10 MBq)
- ✓ Storage cabinets (antistatic, desiccator) for components and assembled modules
- ✓ ...

# Concept Design of ALICE/ITS Module Assembly

## Timescale:

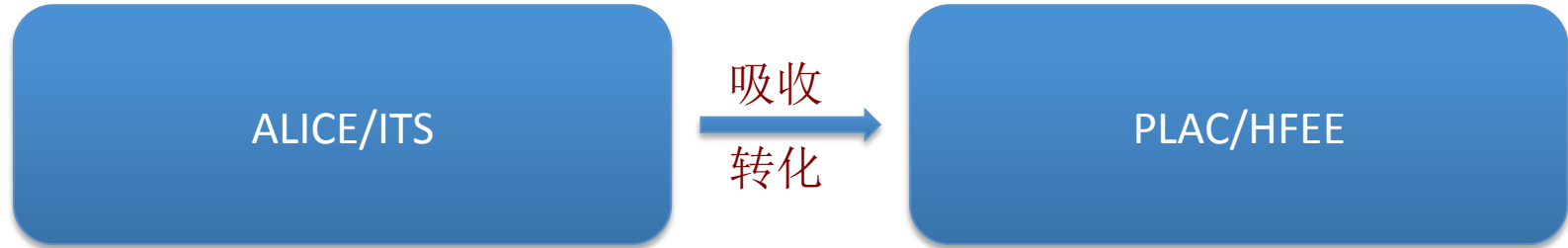
- Setting up of the infrastructures and training next year.
- Start module production mid 2016.

	2015				2016				2017			
	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4
Laboratory setting up												
Automatic Assembly System: Procurement, Installation and Commissioning												
Training (@ CERN and Bari/Italy)												
Manual assembly and Laser soldering												
Automatic assembly system												
Test System												
Module Production												



# Conclusion and Outlook

Transfer what we learned from the ALICE/ITS module assembly to PLAC/HFEE applications?



Several automatic options can be done by mean of vision system:

- Automatic chip visual inspection
- Fully automatic chip placement/alignment
- Automatic FPC placement/alignment?
- Automatic placement of soldering balls
- Quality control of soldering joints by vision system
- Chip electrical test?

# Conclusion and Outlook – We have a plan!





**Thanks!**